

# ADJUSTABLE PRECISION ZENER SHUNT REGULATOR

ISSUE 4 – SEPTEMBER 2000

ZR431

## DEVICE DESCRIPTION

The ZR431 is a three terminal adjustable shunt regulator offering excellent temperature stability and output current handling capability up to 100mA. The output voltage may be set to any chosen voltage between 2.5 and 20 volts by selection of two external divider resistors.

The devices can be used as a replacement for zener diodes in many applications requiring an improvement in zener performance.

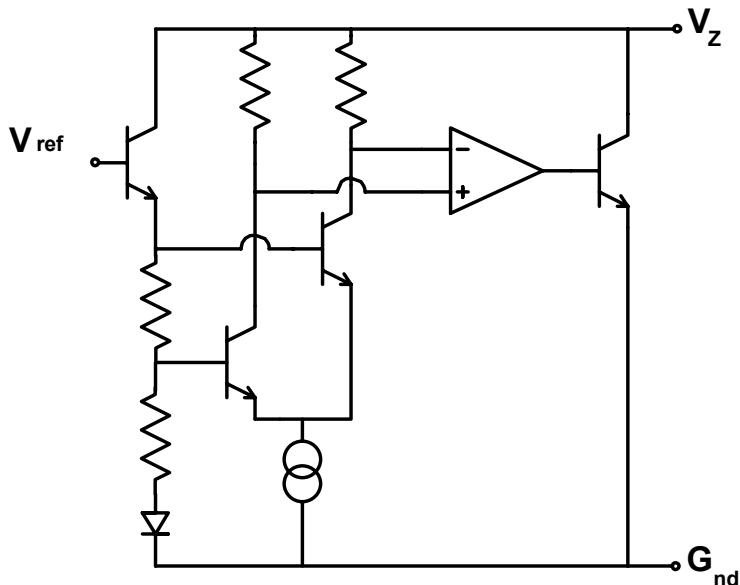
## FEATURES

- Surface mount SO8, SOT223 and SOT23 packages
- TO92 package
- 2%, 1 % and 0.5% tolerance
- Max. temperature coefficient 55 ppm/ $^{\circ}$ C
- Temperature compensated for operation over the full temperature range
- Programmable output voltage
- 50 $\mu$ A to 100mA current sink capability
- Low output noise

## APPLICATIONS

- Shunt regulator
- Series regulator
- Voltage monitor
- Over voltage/ under voltage protection
- Switch mode power supplies

## SCHEMATIC DIAGRAM



 **ZETEX**

# ZR431

## ABSOLUTE MAXIMUM RATING

|   |              |  |  |  |
|---|--------------|--|--|--|
| Cathode Voltage (Vz)                    | 20V          | Power Dissipation ( $T_{amb}=25^{\circ}C, T_{jmax}=150^{\circ}C$ ) |  |  |
| Cathode Current                         | 150mA        | SOT23 330mW  |  |  |
| Operating Temperature                   | -40 to 85°C  | TO92 780mW   |  |  |
| Storage Temperature                     | -55 to 125°C | SOT223 2W  |  |  |
| <b>Recommended Operating Conditions</b> |              |  |  |  |
|   | Min          | Max  |  |  |
| Cathode Voltage                         | Vref         | 20V  |  |  |
| Cathode Current                         | 50µA         | 100mA  |  |  |

ELECTRICAL CHARACTERISTICS TEST CONDITIONS (Unless otherwise stated):  $T_{amb}=25^{\circ}C$

| PARAMETER   | SYMBOL                              | VALUE |       |       | UNITS | CONDITIONS   |
|---|-------------------------------------|-------|-------|-------|-------|--|
|   |                                     | MIN   | _TYP  | MAX   |       |  |
| Reference Voltage<br><sup>(1)</sup> 0.5%                                  | V <sub>ref</sub>                    | 2.45  | 2.50  | 2.55  | V     | $I_L=10mA$ (Fig1), $V_Z=V_{ref}$                       |
|   |                                     | 2.475 | 2.50  | 2.525 |       |  |
|   |                                     | 2.489 | 2.50  | 2.513 |       |  |
| Deviation of Reference Input Voltage over Temperature                     | V <sub>dev</sub>                    |       | 8.0   | 17    | mV    | $I_L=10mA$ , $V_Z=V_{ref}$<br>$T_a=$ full range (Fig1) |
| Ratio of the change in Reference Voltage to the Change in Cathode Voltage | $\frac{\Delta V_{ref}}{\Delta V_Z}$ |       | -1.85 | -2.7  | mV/V  | $V_Z$ from $V_{ref}$ to 10V<br>$I_Z=10mA$ (Fig2)       |
|   |                                     |       | -1.0  | -2.0  | mV/V  | $V_Z$ from 10V to 20V<br>$I_Z=10mA$ (Fig2)             |
| Reference Input Current   | I <sub>ref</sub>                    |       | 0.12  | 1.0   | µA    | R1=10k, R2=O/C, $I_L=10mA$ (Fig2)                      |
| Deviation of Reference Input Current over Temperature                     | $\Delta I_{ref}$                    |       | 0.04  | 0.2   | µA    | R1=10k, R2=O/C, $I_L=10mA$<br>$T_a=$ full range (Fig2) |
| Minimum Cathode Current for Regulation                                    | I <sub>Zmin</sub>                   |       | 35    | 50    | µA    | $V_Z=V_{ref}$ (Fig1)                                   |
| Off-state Current   | I <sub>Zoff</sub>                   |       |       | 0.1   | µA    | $V_Z=20V$ , $V_{ref}=0V$ (Fig3)                        |
| Dynamic Output Impedance  | R <sub>Z</sub>                      |       |       | 0.75  | Ω     | $V_Z=V_{ref}$ (Fig1), f=0Hz                            |

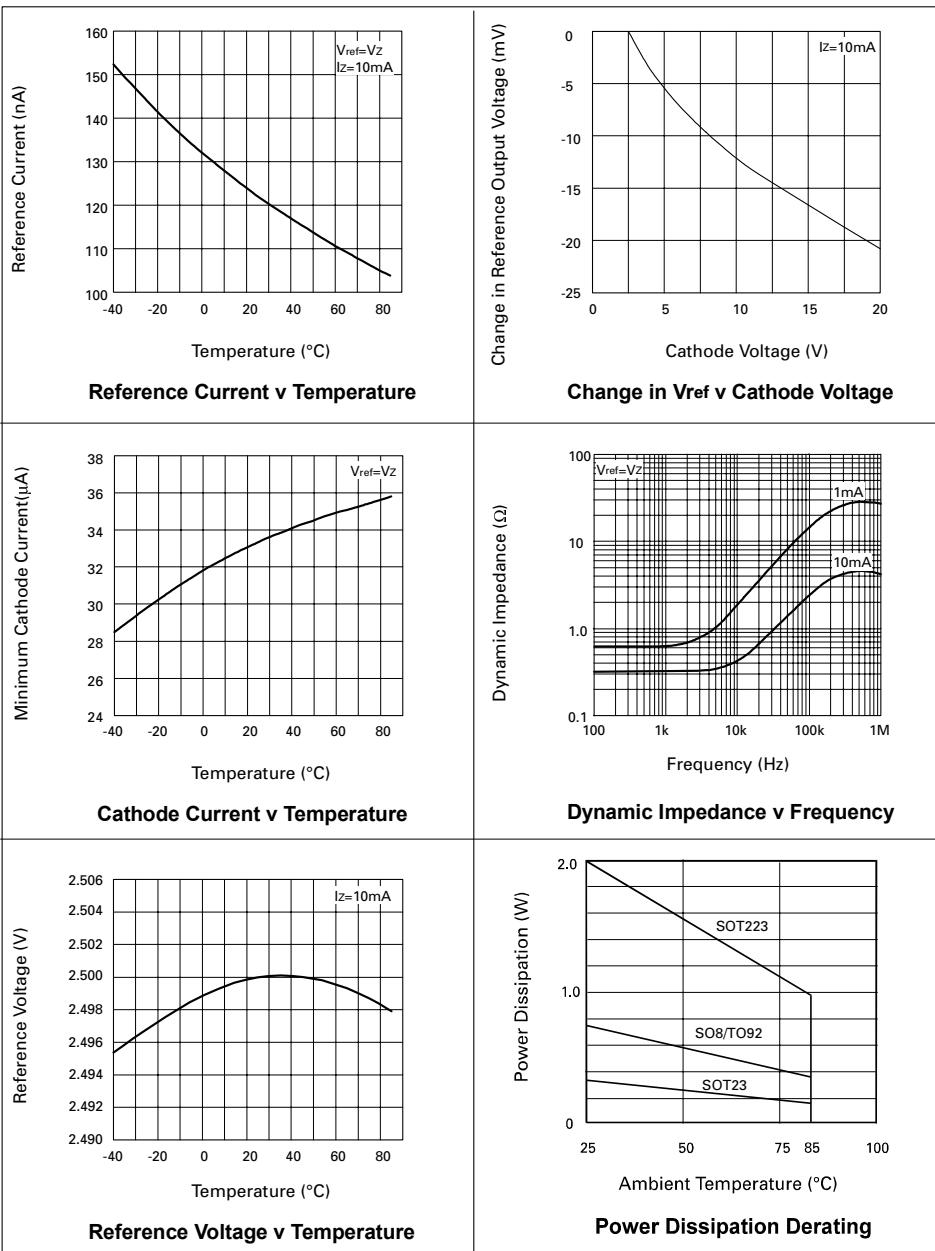
<sup>(1)</sup> 0.5% SOT23 only.

For definitions of reference voltage temperature coefficient and dynamic output impedance see NOTES following DC TEST CIRCUITS



**ZR431**

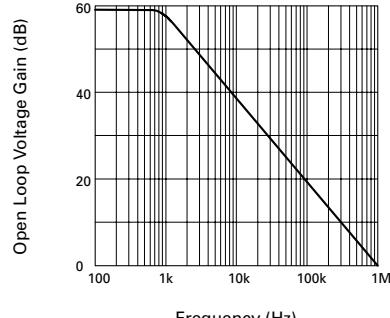
## TYPICAL CHARACTERISTICS



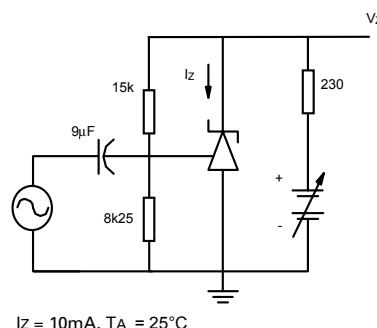
 **ZETEX**

# ZR431

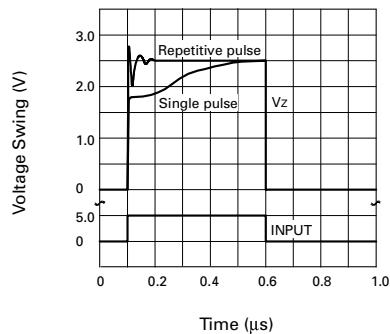
## TYPICAL CHARACTERISTICS



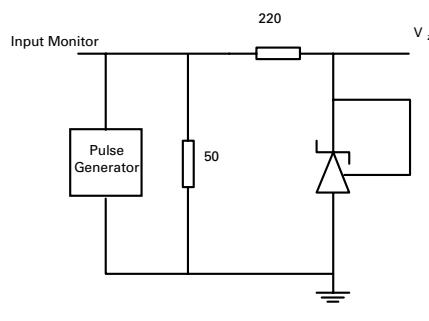
**Gain v Frequency**



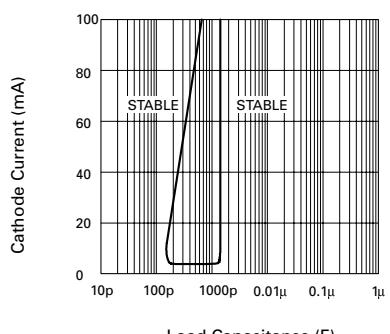
**Test Circuit for Open Loop Voltage Gain**



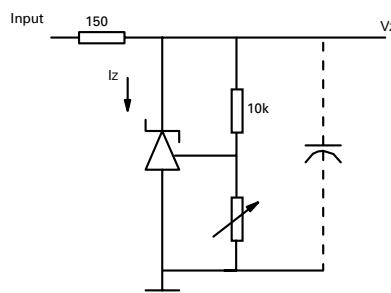
**Pulse Response**



**Test Circuit for Pulse Response**



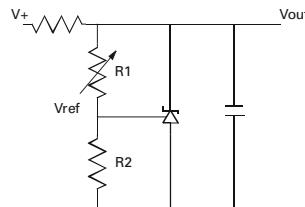
**Stability Boundary Conditions**



$V_{\text{ref}} < V_Z < 20$ ,  $I_Z = 10\text{mA}$ ,  $T_A = 25^\circ\text{C}$

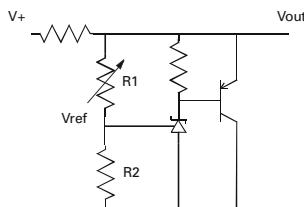
**Test Circuit for Stability Boundary Conditions**

## APPLICATION CIRCUITS



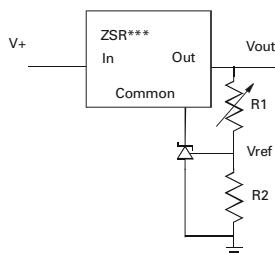
$$V_{out} = \left(1 + \frac{R_1}{R_2}\right) V_{ref}$$

SHUNT REGULATOR



$$V_{out} = \left(1 + \frac{R_1}{R_2}\right) V_{ref}$$

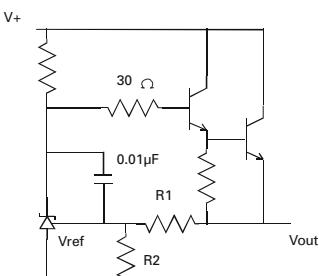
HIGHER CURRENT SHUNT REGULATOR



$$V_{out\_MIN} = V_{ref} + V_{reg}$$

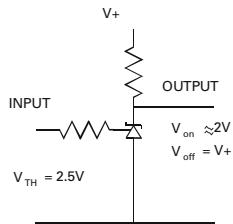
$$V_{out} = \left(1 + \frac{R_1}{R_2}\right) V_{ref}$$

OUTPUT CONTROL OF A THREE TERMINAL FIXED REGULATOR

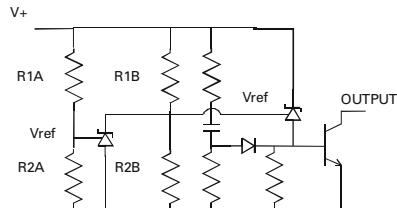


$$V_{out} = \left(1 + \frac{R_1}{R_2}\right) V_{ref}$$

SERIES REGULATOR



SINGLE SUPPLY COMPARATOR WITH TEMPERATURE COMPENSATED THRESHOLD



$$\text{Low limit} = \left(1 + \frac{R_{1B}}{R_{2B}}\right) V_{ref}$$

$$\text{High limit} = \left(1 + \frac{R_{1A}}{R_{2A}}\right) V_{ref}$$

OVER VOLTAGE / UNDER VOLTAGE PROTECTION CIRCUIT

# ZR431

## DC TEST CIRCUITS

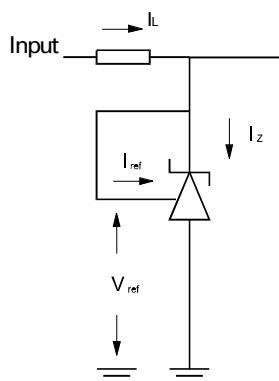


Fig 1 – Test Circuit for  $V_z = V_{\text{ref}}$

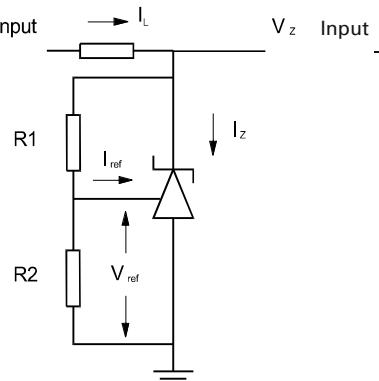


Fig 2 – Test Circuit for  $V_z > V_{\text{ref}}$

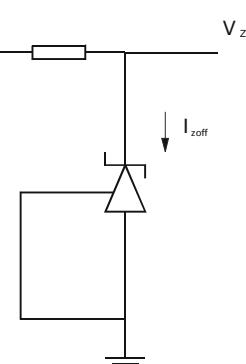
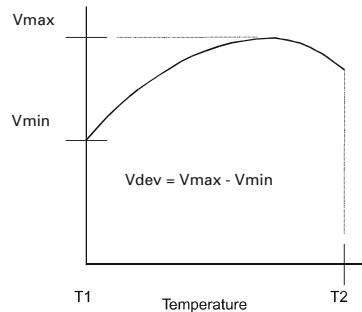


Fig 3 – Test Circuit for Off State current

## NOTES

Deviation of reference input voltage,  $V_{\text{dev}}$ , is defined as the maximum variation of the reference input voltage over the full temperature range.

The average temperature coefficient of the reference input voltage,  $V_{\text{ref}}$  is defined as:



$$V_{\text{ref}} (\text{ppm}/^{\circ}\text{C}) = \frac{V_{\text{dev}} \times 1000000}{V_{\text{ref}} (T_1 - T_2)}$$

The dynamic output impedance,  $R_Z$ , is defined as:

$$R_Z = \frac{\Delta V_Z}{\Delta I_Z}$$

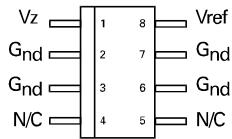
When the device is programmed with two external resistors,  $R_1$  and  $R_2$ , (fig 2), the dynamic output impedance of the overall circuit,  $R'$ , is defined as:

$$R' = R_Z \left(1 + \frac{R_1}{R_2}\right)$$

**ZR431**

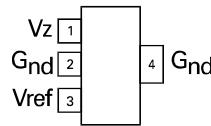
## CONNECTION DIAGRAMS

### SO8 Package Suffix – N8



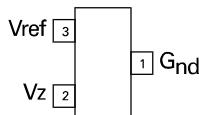
*Top View*

### SOT223 Package Suffix – G



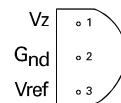
*Top View –  
Pin 4 floating or connected to pin 2*

### SOT23 Package Suffix – F



*Top View*

### TO92 Package Suffix – C



*Bottom View*

## ORDERING INFORMATION

| Part Number | Package | Tol.<br>% | Part Mark |
|-------------|---------|-----------|-----------|
| ZR431C01    | TO92    | 1.0       | ZR43101   |
| ZR431C      | TO92    | 2.0       | ZR431     |
| ZR431G01    | SOT223  | 1.0       | ZR43101   |
| ZR431G      | SOT223  | 2.0       | ZR431     |
| ZR431F005   | SOT23   | 0.5       | 43R       |
| ZR431F01    | SOT23   | 1.0       | 43B       |
| ZR431F      | SOT23   | 2.0       | 43A       |
| ZR431N801   | SO8     | 1.0       | ZR43101   |
| ZR431N8     | SO8     | 2.0       | ZR431     |

 **ZETEX**