



**MODEL: Fusion 7**

**P/N: F07A-0102**

## **PRODUCT SPECIFICATION**

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Version 1.4

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## REVISION HISTORY

| Version # | Implemented By | Revision Date    | Approved By  | Approval Date    | Reason  |
|-----------|----------------|------------------|--------------|------------------|---|
| 1.0       | Alan Dragon    | October 6, 2010  | Mark Hamblin | October 6, 2010  | Rev 1.0 Release                               |
| 1.1       | Alan Dragon    | October 7, 2010  | Mark Hamblin | October 7, 2010  | Update Reliability and Testing                |
| 1.2       | Alan Dragon    | October 21, 2010 | Mark Hamblin | October 21, 2010 | Define signals on touch panel connector       |
| 1.3       | Chris Graham   | May 25, 2011     |              |                  | Updated Mechanical DWG / Doc Cosmetic changes |
| 1.4       | Chris Graham   | August 25, 2011  | Bob Mitton   | October 24, 2011 | Revised document and DWG                      |

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# TABLE OF CONTENTS

|   |           |
|---|-----------|
| <b>1 INTRODUCTION .....</b>                         | <b>1</b>  |
| <b>2 TOUCH MODULE .....</b>                         | <b>2</b>  |
| 2.1 General Specifications.....                     | 2         |
| 2.2 Electrical – Touch Panel.....                   | 2         |
| 2.3 Environmental.....                              | 3         |
| 2.4 Optical Performance.....                        | 4         |
| 2.5 Mechanical Dimensions.....                      | 4         |
| 2.6 FPC Specification .....                         | 5         |
| <b>3 COMMUNICATIONS INTERFACE .....</b>             | <b>6</b>  |
| 3.1 Introduction.....                               | 6         |
| 3.2 I2C interface Specification.....                | 6         |
| 3.3 Touch Panel Connector .....                     | 6         |
| 3.4 Signal Definitions.....                         | 7         |
| 3.5 Communications Protocol.....                    | 7         |
| 3.6 Register Mapped Interface .....                 | 7         |
| 3.6.1 Description.....                              | 7         |
| 3.6.2 Register Map .....                            | 8         |
| 3.7 Register Definitions .....                      | 8         |
| 3.7.1 Touch Coordinate registers .....              | 8         |
| 3.7.2 Control Registers .....                       | 12        |
| 3.7.3 Scan Complete Register (0x11).....            | 13        |
| 3.7.4 Reserved (0x12 – 0x13) .....                  | 13        |
| 3.7.5 Firmware Update Control Register (0x14) ..... | 13        |
| <b>4 LCD INTERFACE.....</b>                         | <b>14</b> |
| 4.1 General Description.....                        | 14        |
| 4.1.1 Introduction.....                             | 14        |
| 4.1.2 Features .....                                | 14        |
| 4.1.3 General Specifications.....                   | 14        |
| 4.2 Absolute Maximum Ratings.....                   | 15        |
| 4.3 Electrical Characteristics .....                | 15        |
| 4.3.1 Recommended Operating Conditions.....         | 15        |
| 4.3.2 LED Driving Conditions.....                   | 16        |
| 4.3.3 TFT-LCD Current Consumption.....              | 16        |
| 4.4 Interface .....                                 | 17        |
| 4.4.1 Timing Signal Characteristics .....           | 17        |
| 4.4.2 Controller Timing Chart.....                  | 18        |

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|          |  |           |
|----------|--|-----------|
| 4.4.3    | Data Input Format.....                 | 18        |
| 4.4.4    | Power ON/OFF Sequence.....             | 19        |
| 4.4.5    | Power ON/OFF timing values .....       | 19        |
| 4.4.6    | LCD Signal Cable Definition .....      | 20        |
| 4.4.7    | Backlight Signal Cable Definition..... | 21        |
| 4.5      | LCD internal Block Diagram .....       | 22        |
| 4.6      | Optical Performance.....               | 22        |
| <b>5</b> | <b>RELIABILITY AND TESTING .....</b>   | <b>23</b> |
| 5.1      | Reliability Test Specifications .....  | 23        |
| 5.2      | Packaging Specifications.....          | 23        |
| <b>6</b> | <b>BARCODE .....</b>                   | <b>24</b> |
| 6.1      | Description.....                       | 24        |
| 6.2      | Location.....                          | 24        |
| 6.3      | Contents .....                         | 24        |
| <b>7</b> | <b>HANDLING AND PRECAUTIONS.....</b>   | <b>25</b> |
| 7.1      | Disassembly or Modification .....      | 25        |
| 7.2      | UV Exposure .....                      | 25        |
| 7.3      | Cleaning .....                         | 25        |
| 7.4      | Static Electricity .....               | 25        |
| 7.5      | Absolute Maximum Ratings.....          | 25        |
| 7.6      | Breakage .....                         | 25        |
| 7.7      | Input Voltages.....                    | 25        |
| 7.8      | Static Images.....                     | 25        |
| 7.9      | Outgassing .....                       | 26        |

## 1 INTRODUCTION

The Fusion 7 is an integrated projected capacitive touch display incorporating a 7", 800 x 480 (WVGA) LCD with a LED backlight. The touch portion of the module consists of a glass sensor optically bonded to 1.0 mm cover glass with an FPC (Flexible Printed Circuit) attached for communicating with the touch panel. The touch panel assembly (sensor plus cover glass) is bonded to the LCD frame.

Interfacing to the touch panel is done through an I2C protocol communicating with the controller incorporated onto the FPC. The touch panel can provide accurate and responsive touch performance capable of sensing two unambiguous points. The integrated configuration of the Fusion touch display gives the user the ability to develop a touch product with a minimum of time and design effort.

## 2 TOUCH MODULE

### 2.1 GENERAL SPECIFICATIONS

*Table 1 - Touch Performance Specification*

| Parameter                                      |                        | Value              | Unit                        | Remarks               |
|--|------------------------|--------------------|-----------------------------|-----------------------|
| Linearity                                      | Center                 | 1                  | mm                          | Note 1,<br>Appendix A |
|  | Within 5mm of the edge | 2                  |                             |                       |
| Touch Sensor Resolution                        |                        | 1550 x 950         | Detectable Resolution       |                       |
| Report Rate                                    | Single Touch           | 100                | Serviced Interrupts/ Second | Note 2,<br>Appendix A |
|  | Dual Touch             | 50                 |                             |                       |
| First Touch Response Time                      |                        | $30 \cdot 10^{-3}$ | sec                         | Note 3,<br>Appendix A |
| Minimum Touch Diameter                         |                        | 7                  | mm                          | Note 4,<br>Appendix A |
| Minimum Detectable Separation                  |                        | 15                 | mm                          |                       |
| Number of unique detectable concurrent touches |                        | 2                  |                             |                       |

### 2.2 ELECTRICAL – TOUCH PANEL

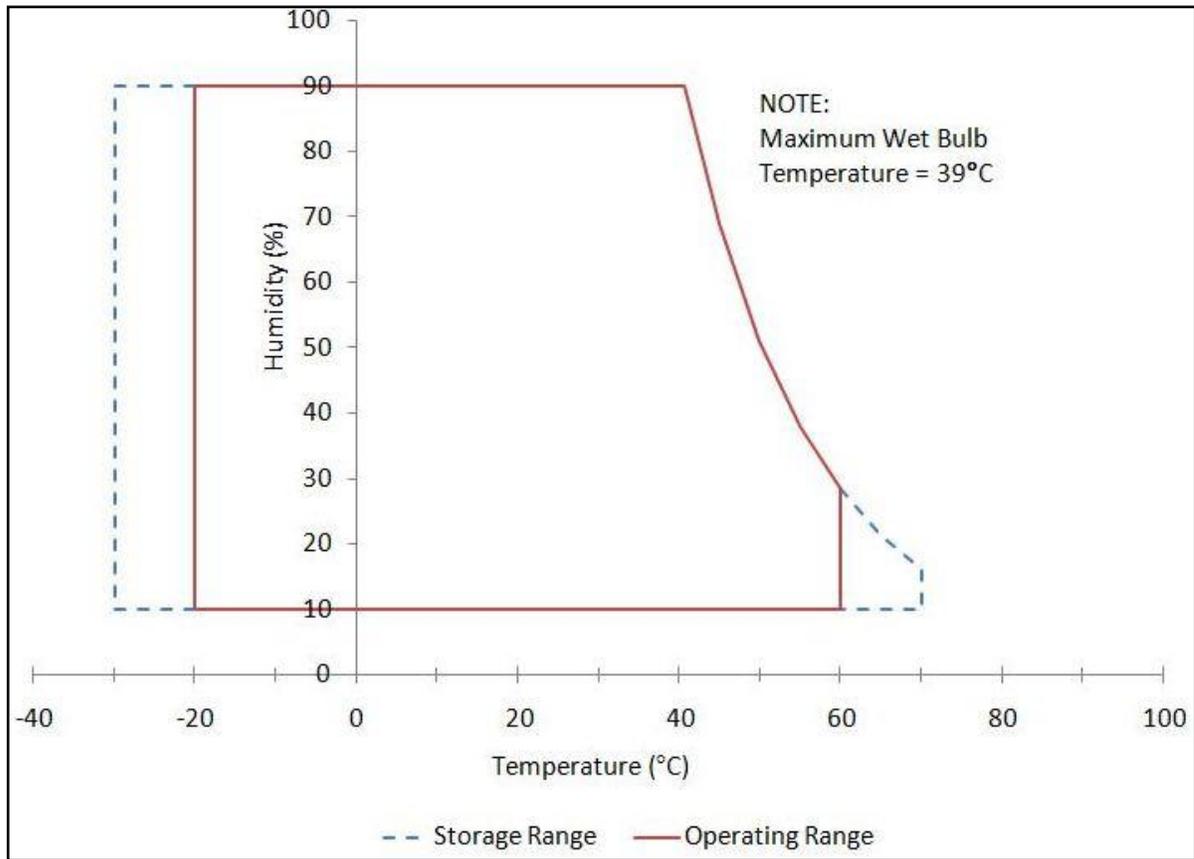
*Table 2 - Electrical Specification*

| Parameter          | Symbol | Value |      |      | Unit |
|--------------------|--------|-------|------|------|------|
|                    |        | Min.  | Typ. | Max  |      |
| Supply voltage     | VCC    | 3.15  | 3.3  | 3.45 | V    |
| Current (no touch) | ICC    | -     | 5.2  | 10.0 | mA   |
| Current (1 touch)  | ICC1   | -     | 5.1  | 10.0 | mA   |
| Current (2 touch)  | ICC2   | -     | 5.0  | 10.0 | mA   |

## 2.3 ENVIRONMENTAL

**Table 3 - Environmental Specification**

| Parameter             | Value      | Unit |
|-----------------------|------------|------|
| Operating Temperature | -20 to +60 | °C   |
| Storage Temperature   | -30 to +70 | °C   |



**Figure 1 - Operating Temperature and Humidity Range**

## 2.4 OPTICAL PERFORMANCE

*Table 4 - Optical Performance Specification*

| Parameter                            |       | Value          |          | Unit              | Remarks             |
|--------------------------------------|-------|----------------|----------|-------------------|---------------------|
| Optical Transmittance of Touch Panel |       | >89            |          | %                 | Note 5, Appendix A  |
| Light Output without touch panel     |       | Min.=300       | Typ.=350 | cd/m <sup>2</sup> | Center of the Panel |
| Light Output with Touch Panel        |       | Min.=265       | Typ.=310 | cd/m <sup>2</sup> | Center of the Panel |
| Viewing Angle                        | Hor.  | Θ <sub>L</sub> | Min.=60  | Typ.=70           | Deg.                |
|                                      |       | Θ <sub>R</sub> | Min.=60  | Typ.=70           |                     |
|                                      | Vert. | Φ <sub>T</sub> | Min.=50  | Typ.=60           | Deg.                |
|                                      |       | Φ <sub>B</sub> | Min.=60  | Typ.=70           |                     |

## 2.5 MECHANICAL DIMENSIONS

*Table 5 - Mechanical Specification*

| Parameter                    | Value                  | Unit            | Remarks                |
|------------------------------|------------------------|-----------------|------------------------|
| Outline Dimension            | 179.96 x 119.00 x 7.50 | mm              | Appendix B             |
| Active Area                  | 152.40(H) x 91.44(V)   | mm              | LCD, Touch Sensor      |
| Weight                       | 210.5 (Typ.)           | grams           |                        |
| Cover Glass Surface Hardness | >9H                    | Pencil Hardness | See Note 7, Appendix A |

## 2.6 FPC SPECIFICATION

The flexible segment (any portion without a stiffener) of the signal FPC from the touch panel has a minimum bend radius  $\geq 1.0\text{mm}$ . The image below shows the FPC with the stiff areas outlined in red. Stiff areas are not designed to be bent or deformed.

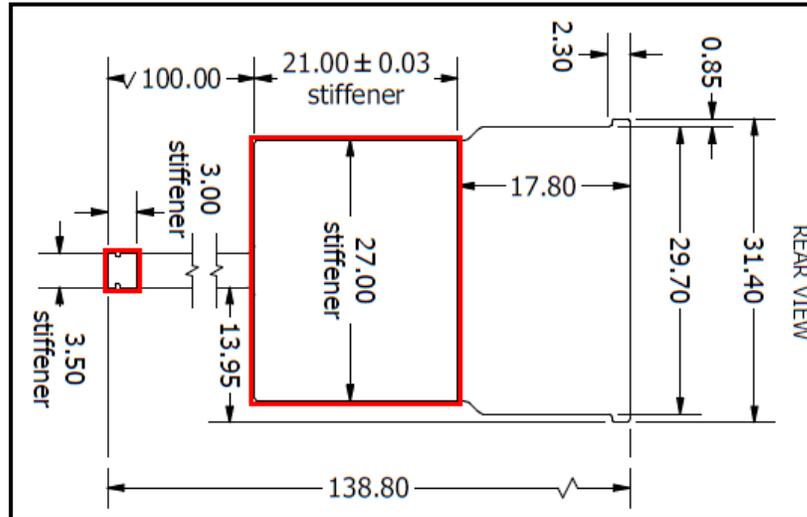


Figure 2 - FPC Stiffener Areas

## 3 COMMUNICATIONS INTERFACE

### 3.1 INTRODUCTION

The touch panel communicates with a host processor through an I2C interface. An edge sensitive interrupt output indicates when new touch points have been detected. In a normal system setup the rising edge of the interrupt will cause the host processor to read the coordinate data through the I2C bus. The coordinate data is stored in a register mapped array that is defined section 3.6.2.

### 3.2 I2C INTERFACE SPECIFICATION

The touch panel supports a NXP compliant I2C interface<sup>1</sup>. The slave address for the touch controller is 7 bit 0x10, followed by the R/W bit. The I2C bus supports the standard bus speed of 100 kHz and fast 400 kHz.

External pull up resistors are required on the I2C clock and data lines. Refer to UM10204 I2C-Bus Specification and User Manual when selecting pull-up resistor values to ensure proper operation.

### 3.3 TOUCH PANEL CONNECTOR

The recommended touch panel connector is: Kyocera-Elco 6-pin P/N 04-6298-006000883. The pin out for the Kyocera connector is as noted in the following table.

**Table 6 - Touch Panel Connector Pinout – Refer to Mechanical Drawings for Pin 1 Orientation**

| Pin No. | Symbol | Description    |
|---------|--------|----------------|
| 1       | VCC    | Power supply   |
| 2       | RST    | Reset          |
| 3       | INT    | Interrupt      |
| 4       | SDA    | I2C data line  |
| 5       | SCL    | I2C clock line |
| 6       | GND    | Ground         |

<sup>1</sup> The specification for the NXP compliant I2C interface is *UM10204 I2C-Bus Specification and User Manual, Rev. 03—19 June 2007*. It is available from NXP Semiconductor at [http://www.nxp.com/documents/user\\_manual/UM10204.pdf](http://www.nxp.com/documents/user_manual/UM10204.pdf).

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### 3.4 SIGNAL DEFINITIONS

- VCC - Power supply for the touch controller.
- RST - Reset for the touch controller. Should be connected to a reset line. This reset is asserted low (0V). When not asserted it should be raised to VCC.
- INT - Interrupt from the touch controller. This should be connected to an interrupt enabled IO. This output is asserted high to VCC when touch data is ready. This interrupt should be treated as an edge sensitive signal.
- SDA - Data line of I2C connection. This signal should be connected to the data line of an I2C bus. This I2C bus should have pull-up resistors to VCC. The touch controller does not contain pull-ups resistors
- SCL - Clock line of I2C connection. This signal should be connected to the clock line of an I2C bus. This I2C bus should have pull-up resistors to VCC. The touch controller does not contain pull-ups resistors.
- GND - Digital Ground.

### 3.5 COMMUNICATIONS PROTOCOL

The Touch controller is designed to work in an interrupt driven protocol. When the Touch panel is touched and data is ready for the host processor it asserts the interrupt line to the processor. The processor should then read the data registers and once it is finished it must clear the interrupt in the controller by writing a 0 to the scan complete bit of the Handshaking control register.

The I2C data will not change until the scan complete bit is cleared by the host processor. Once the scan complete bit is cleared the controller will resume scanning the sensor.

### 3.6 REGISTER MAPPED INTERFACE

#### 3.6.1 Description

A set of logical registers is defined and exposed by the touch panel controller. The host communicates with the controller by reading and writing the exposed registers via physical I2C transactions. All registers are 8 bits in length. Multi-byte data words are spread across multiple registers. An 8-bit I2C address is used to uniquely identify each register.

### 3.6.2 Register Map

The following table defines the location of each value in the register map.

*Table 7 – Register Map*

| Address     | Purpose                                  | Accessibility |
|-------------|--|---------------|
| 0x00 – 0x00 | Data Information Register                | R             |
| 0x01 - 0x06 | First Touch Point Information Registers  | R             |
| 0x07 – 0x0C | Second Touch Point Information Registers | R             |
| 0x0D – 0x0D | Register Map Version                     | R             |
| 0x0E – 0x0F | Firmware Version Register                | R             |
| 0x10 – 0x10 | Reset Control Register                   | W             |
| 0x11 – 0x11 | Scan Complete Register                   | R/W           |
| 0x12 – 0x13 | Reserved                                 | R             |
| 0x14 – 0x14 | Firmware Update Control Register         | W             |

## 3.7 REGISTER DEFINITIONS

### 3.7.1 Touch Coordinate registers

#### 3.7.1.1 Data Information Register (0x00)

|      | 7 | 6 | 5 | 4 | 3 | 2 | 1                 | 0 |
|------|---|---|---|---|---|---|-------------------|---|
| 0x00 | - | - | - | - | - | - | Number of Fingers |   |

- Bits [1:0] indicate the number of fingers touching the panel at the time of the last interrupt.
  - {00} = 0 fingers
  - {01} = 1 finger
  - {10} = 2 fingers
  - {11} = not defined

Note: After the first touch, this register does not indicate when there are no fingers touching the sensor because interrupts are not triggered on the finger-up or '0 finger' event. The data remaining in this register is the number of fingers touching the sensor at the time of the most recent interrupt. It will always be 1 or 2 after the first interrupt after power-up or reset. To determine if there are no fingers touching the sensor use the tip switch value in register 0x06.

### 3.7.1.2 First Touch Point Information Registers (0x01 – 0x06)

|      | 7                                | 6 | 5 | 4 | 3          | 2 | 1 | 0 |
|------|----------------------------------|---|---|---|------------|---|---|---|
| 0x01 | X0 Position (bits 15:8)          |   |   |   |            |   |   |   |
| 0x02 | X0 Position (bits 7:0)           |   |   |   |            |   |   |   |
| 0x03 | Y0 Position (bits 15:8)          |   |   |   |            |   |   |   |
| 0x04 | Y0 Position (bits 7:0)           |   |   |   |            |   |   |   |
| 0x05 | First Touch Point Pressure Value |   |   |   |            |   |   |   |
| 0x06 | Touch ID                         |   |   |   | Tip Switch |   |   |   |

All touch point information registers are read only.

- Registers 0x01 – 0x04
  - The coordinates for the first touch point are in registers 0x01 – 0x04 as defined above.
  - The value is reported as a 16 bit value with the maximum value equal to the resolution of the sensor.
- Register 0x05
  - This register returns a pressure value for the touch point. The pressure value is representative of the diameter of the contact area touching the sensor.
  - This value is an 8 bit number. The value is not normalized so it should be interpreted as a relative number.
- Register 0x06

|      | 7        | 6 | 5 | 4 | 3          | 2 | 1 | 0 |
|------|----------|---|---|---|------------|---|---|---|
| 0x06 | Touch ID |   |   |   | Tip Switch |   |   |   |

- Bits 3:0 indicate if the current touch point is touching the screen. This field should be used to determine when a touch point is detected and also when it is lifted from the screen.
  - {0000} = This value indicates the finger is not touching the screen for the current coordinate point.
  - {0001} = This value indicates the finger is touching the screen for the current coordinate point.
  - All other combinations are not defined.
- Bits 7:4 represent a unique ID to differentiate between 2 different fingers under the case where the data for the fingers switches

between the first touch point and the second touch point. This can be used to maintain tracking information between 2 different fingers.

### 3.7.1.3 Second Touch Point Information Registers (0x07 – 0x0C)

|      |                                   |   |   |   |            |   |   |   |
|------|-----------------------------------|---|---|---|------------|---|---|---|
|      | 7                                 | 6 | 5 | 4 | 3          | 2 | 1 | 0 |
| 0x07 | X1 Position (bits 15:8)           |   |   |   |            |   |   |   |
| 0x08 | X1 Position (bits 7:0)            |   |   |   |            |   |   |   |
| 0x09 | Y1 Position (bits 15:8)           |   |   |   |            |   |   |   |
| 0x0A | Y1 Position (bits 7:0)            |   |   |   |            |   |   |   |
| 0x0B | Second Touch Point Pressure Value |   |   |   |            |   |   |   |
| 0x0C | Touch ID                          |   |   |   | Tip Switch |   |   |   |

The coordinates of the second touch point are reported via registers 0x07 to 0x0C. These registers are Read-Only and only valid when more than one finger is reported in the Data Information Register and the Tip Switch is asserted.

- Registers 0x07 – 0x0A
  - The coordinates for the second touch point are in registers 0x07 – 0x0A as defined above.
  - The value is reported as a 16 bit value with the maximum value equal to the resolution of the sensor.
- Register 0x0B
  - This register returns a pressure value for the touch point. The pressure value is representative of the diameter of the contact area touching the sensor.
  - This value is an 8 bit number. The value is not normalized so it should be interpreted as a relative number.
- Register 0x0C

|      |          |   |   |   |            |   |   |   |
|------|----------|---|---|---|------------|---|---|---|
|      | 7        | 6 | 5 | 4 | 3          | 2 | 1 | 0 |
| 0x0C | Touch ID |   |   |   | Tip Switch |   |   |   |

- Bits 3:0 indicate if the current touch point is touching the screen. This field should be used to determine when a touch point is detected and also when it is lifted from the screen.
  - {0000} = This value indicates the finger is not touching the screen for the current coordinate point.

- {0001} = This value indicates the finger is touching the screen for the current coordinate point.
- All other combinations are not defined.
- Bits 7:4 represent a unique ID to differentiate between 2 different fingers under the case where the data for the fingers switches between the first touch point and the second touch point. This can be used to maintain tracking information between 2 different fingers.

**3.7.1.4 Register map version (0x0D)**

|      |                            |   |   |   |   |   |   |   |
|------|----------------------------|---|---|---|---|---|---|---|
|      | 7                          | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x0D | Register map version (7:0) |   |   |   |   |   |   |   |

This register dictates the register map. This register can be queried by the host to determine which register values are located at which register offsets. For the register map corresponding to this document the value will be 0x02.

**3.7.1.5 Firmware Version Register (0x0E - 0x0F)**

|      |              |   |      |   |                  |   |         |   |
|------|--------------|---|------|---|------------------|---|---------|---|
|      | 7            | 6 | 5    | 4 | 3                | 2 | 1       | 0 |
| 0x0E | Product Info |   | Year |   | Month            |   |         |   |
| 0x0F | Day          |   |      |   | Firmware Version |   | Release |   |

Firmware releases are numbered by the following format: yyyyymmddx where yyyyymmdd is the date of release and x is the running number of the release in case there are multiple releases on a given day.

To store the version information, two registers (0x0D – 0x0E) are used and defined as follows:

- Register 0x0E
  - Bits 7:6 represent Product Information (Read Only)
    - {00} = 43Z6 = 4.3” Panel
    - {01} = 70Z7 = 7” Panel
    - {10} = 10Z8 = 10.1” Panel
    - {11} = Reserved
  - Bits 5:4 represent the Year (Read Only)
    - {00} = 2010

- {01} = 2011
- {10} = 2012
- {11} = 2013

Bits 3:0 represent the Month (Read Only)

- {0x1} = January
- {0x2} = February
- {0x.} = .....
- {0x.} = .....
- {0xC} = December

○ Register 0x0F

Bits 7:3 represent the Day (Read Only)

- {0x01} = 1
- {0x02} = 2
- {0x.} = .....
- {0x.} = .....
- {0x1F} = 31

Bits 2:1 represent the Firmware Version (Read Only)

- {00} = v1.0 Firmware Architecture
- {01} = v1.4 Firmware Architecture

Bit 0 represents the Release (Read Only)

- {00} = First release of the day.
- {11} = Second release of the day.

Note: More than 2 releases are not expected in one day.

### 3.7.2 Control Registers

#### 3.7.2.1 Reset Control Register (0x10)

|      |       |   |   |   |   |   |   |   |
|------|-------|---|---|---|---|---|---|---|
|      | 7     | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x10 | Reset | - | - | - | - | - | - | - |

This register can be used to trigger a software initiated reset. This reset will clear out all data in the sensor. The busy register will be reset to 0x00. During a software initiated reset the device will not be available on the I2C bus and the interrupt pin will stay low. The system will be available 125 ms after the reset is triggered.

○ Register 0x10

- Bit 7 = reset bit. This bit is write only. Writing a 1 to this bit initiates the reset.
- Bits 6:0 = reserved.

**3.7.3 Scan Complete Register (0x11)**

|      |   |   |   |   |   |   |   |               |
|------|---|---|---|---|---|---|---|---------------|
|      | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0             |
| 0x11 | - | - | - | - | - | - | - | Scan Complete |

This register is used to indicate that data is ready for the Host processor to read. When data is ready to be read the touch controller will not update the data until the host processor indicates it has completed gathering all data for this interrupt.

- Registers 0x11
  - Bit 0 represents Scan Complete(Read and Write)
  - {0} indicates that there is no new data for the Host processor. When this bit is {0} the touch controller is continually scanning the touch panel for new touch events.
  - {1} indicates current scan cycle has been completed and new data is ready for the Host processor.
  - This bit will mimic the interrupt output of the touch controller.
  - The Host should clear this bit (Write “0”) to indicate that a data transfer has been completed and subsequent scan can be started.

**3.7.4 Reserved (0x12 – 0x13)**

**3.7.5 Firmware Update Control Register (0x14)**

|      |                        |   |   |   |   |   |   |   |
|------|------------------------|---|---|---|---|---|---|---|
|      | 7                      | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x14 | Enter Firmware Update- |   |   |   |   |   |   |   |

- Register 0x14
  - Bits 7:0 represents Enter Firmware Update (Write Only)  
Host should write 0x4C to register 0x14 set a flag which will force the controller to boot into firmware update mode on its next power cycle, soft reset or hard reset.

## 4 LCD INTERFACE

### 4.1 GENERAL DESCRIPTION

#### 4.1.1 Introduction

The Fusion 7 incorporates a color active matrix thin film transistor (TFT) liquid crystal display (LCD) that uses amorphous silicon TFT switching device. The LCD assembly is composed of a TFT LCD panel, a driving circuit, and LED backlight system. The display has a 7.0 inch diagonally measured active display area with an 800H x 480V (WVGA) display format that can display 262,144 colors.

#### 4.1.2 Features

- 7.0" (16:9) inch diagonal configuration
- 800H x 480V (WVGA) Pixel Format
- 3.3V TTL Interface
- 262K colors using a 18 bit R.G.B. signal input

#### 4.1.3 General Specifications

*Table 8 - LCD Specifications*

| Parameter             | Specifications(LCD Only)        | Unit   |
|-----------------------|---------------------------------|--------|
| Screen Size           | 7.0" (Diagonal)                 |        |
| Display Format        | 800 RGB(H)X 480(V) (WVGA)       | pixels |
| Pixel Configuration   | RGB Vertical Stripe             |        |
| Active Area           | 152.40 x 91.44                  | mm     |
| Pixel Pitch           | 0.1905 x 0.1905                 | mm     |
| Outline Dimension     | 165.00(W) x 104.44(H) x 5.20(D) | mm     |
| Backlight             | White LED                       |        |
| Power Consumption     | 0.66W(Logic)/ 1.6W(Backlight)   | Watt   |
| Operating Temperature | -20 ~ 70                        | °C     |
| Storage Temperature   | -30 ~ 80                        | °C     |
| Bits per pixel        | 18                              |        |

## 4.2 ABSOLUTE MAXIMUM RATINGS

*Table 9 - LCD Maximum Ratings (GND=0V)*

| Item                | Symbol | Condition | Min. | Max.    | Unit | Remark |
|---------------------|--------|-----------|------|---------|------|--------|
| Power Voltage       | VCC    | GND=0     | -0.3 | 6       | V    | -      |
| Input Logic Voltage | Vi     | GND=0     | -0.3 | VCC+0.3 | V    | Note 1 |

*Note 1: DCLK, DE, R0 ~ R5, G0 ~ G5, B0 ~ B5*

## 4.3 ELECTRICAL CHARACTERISTICS

### 4.3.1 Recommended Operating Conditions

*Table 10 - LCD Recommended Operating Conditions (GND=0V, Ta=25°C)*

| Parameter            |            | Symbol | Rating |      |        | Unit | Condition |
|----------------------|------------|--------|--------|------|--------|------|-----------|
|                      |            |        | Min.   | Typ. | Max.   |      |           |
| Power Supply Voltage |            | VCC    | 3.0    | 3.3  | 3.6    | V    |           |
| Input Logic Voltage  | High Level | VIH    | 0.7VCC | -    | VCC    | V    | Note 1    |
|                      | Low Level  | VIL    | 0      | -    | 0.3VCC | V    | Note1     |

*Note 1: DCLK, DE, R0 ~ R5, G0 ~ G5, B0 ~ B5*

### 4.3.2 LED Driving Conditions

Table 11 - LED Driving Conditions (Ta = 25°C)

| Parameter   | Symbol           | Min.   | Typ.   | Max. | Unit | Remark |
|-------------|------------------|--------|--------|------|------|--------|
| LED Current | I <sub>LED</sub> | -      | 160    | -    | mA   | Note 1 |
| LED Voltage | V <sub>LED</sub> | -      | 9.9    | -    | V    |        |
| LED Life    | -                | 10,000 | 20,000 | -    | Hr.  | Note 2 |

Note 1: There are 8 groups of LEDs as shown below, V<sub>LED</sub>=9.9V, I<sub>LED</sub>=160mA.

Note 2: Light output is decreased to 50% of the initial value.

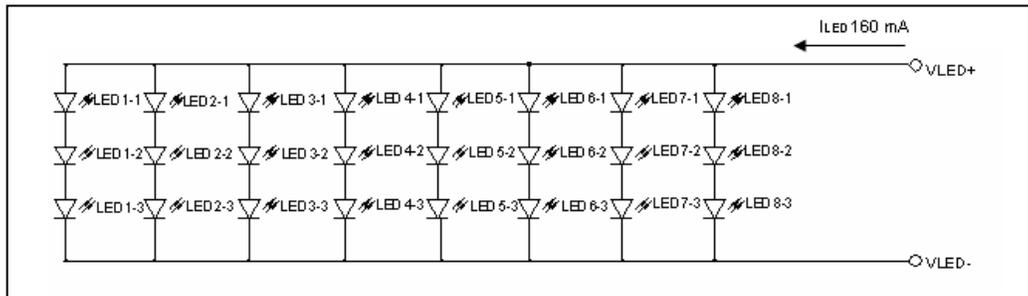


Figure 3 - LED Configuration

### 4.3.3 TFT-LCD Current Consumption

Table 12 - LCD Current Consumption

| Parameter         | Symbol           | Rating |      |      | Unit | Condition     |
|-------------------|------------------|--------|------|------|------|---------------|
|                   |                  | Min.   | Typ. | Max. |      |               |
| LCD Power Current | I <sub>CC</sub>  | -      | 200  | 260  | mA   | Black Pattern |
| LED Power Current | I <sub>LED</sub> | -      | 160  | 200  | mA   |               |

## 4.4 INTERFACE

### 4.4.1 Timing Signal Characteristics

*Table 13 - LCD Signal Timing Characteristics*

| Parameter         | Symbol    | Rating |       |       | Unit      |
|-------------------|-----------|--------|-------|-------|-----------|
|                   |           | Min.   | Typ.  | Max.  |           |
| Data Setup Time   | Tdsu      | 6      | -     | -     | ns        |
| Data Hold Time    | Tdhd      | 6      | -     | -     | ns        |
| DE Setup Time     | Tesu      | 6      | -     | -     | ns        |
| CLK Frequency     | FCPH      | 29.40  | 33.26 | 42.48 | MHz       |
| CLK Period        | TCPH      | 23.54  | 30.06 | 34.01 | ns        |
| CLK Pulse Duty    | TCWH      | 40     | 50    | 60    | %         |
| CLK Pulse Duty    | TCWL      | 40     | 50    | 60    | %         |
| DE Period         | TDEH+TDEL | 1000   | 1056  | 1200  | TCPH      |
| DE Pulse Width    | TDEH      | -      | 800   | -     | TCPH      |
| DE Frame Blanking | TDEB      | 10     | 45    | 110   | TDEH+TDEL |
| DE Frame Width    | TDE       | -      | 480   | -     | TDEH+TDEL |

*Note: Using the typical values will give better performance.*

### 4.4.2 Controller Timing Chart

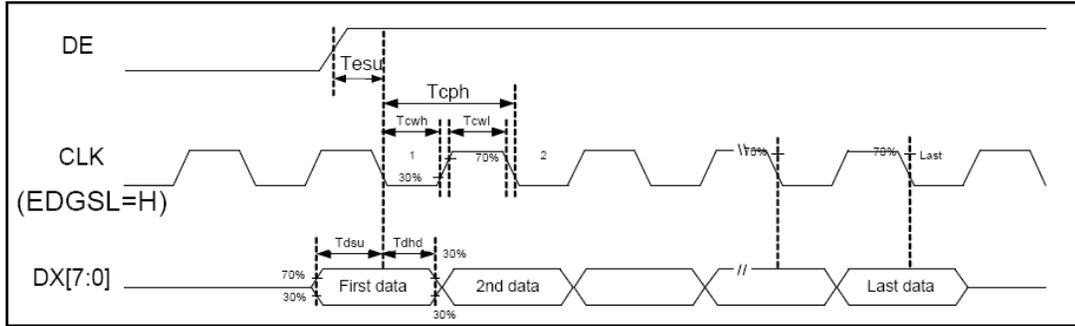


Figure 4 - LCD Interface Waveform

### 4.4.3 Data Input Format

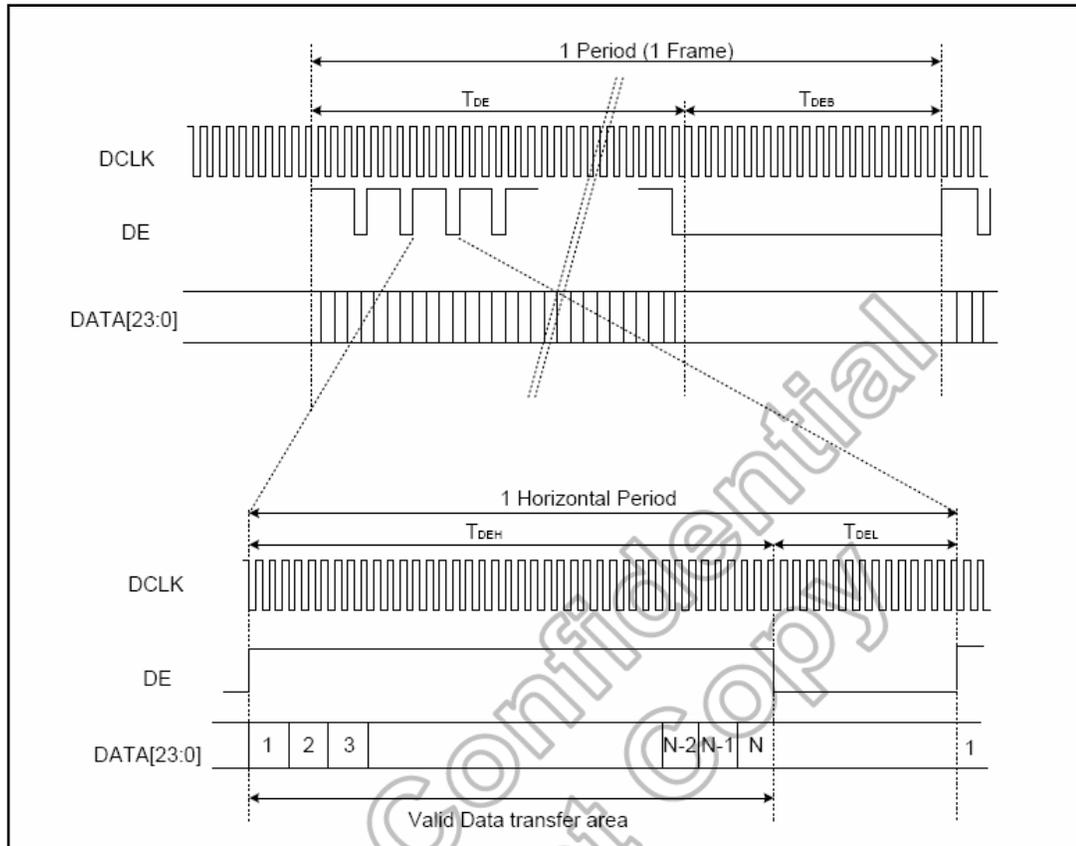


Figure 5 - LCD Data Format

#### 4.4.4 Power ON/OFF Sequence

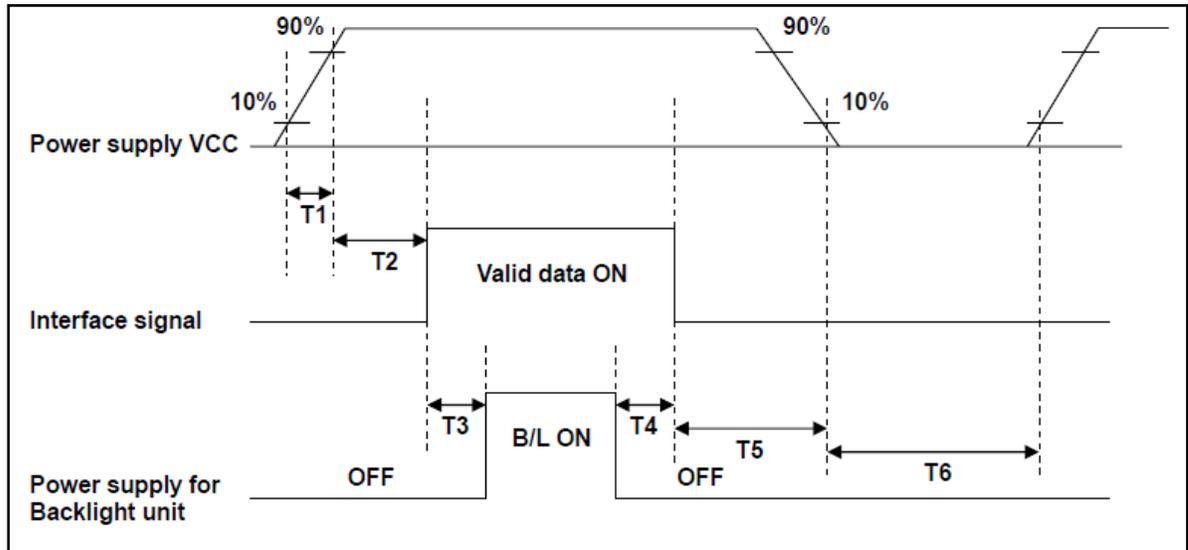


Figure 6 – Power Sequence

#### 4.4.5 Power ON/OFF timing values

Table 14 - Power ON/OFF Timing Values

| Parameter | Specification |      |      | Unit |
|-----------|---------------|------|------|------|
|           | Min.          | Typ. | Max. |      |
| T1        | 1             |      | 2    | ms   |
| T2        | 0             | 60   |      | ms   |
| T3        | 200           |      |      | ms   |
| T4        | 200           |      |      | ms   |
| T5        | 1             |      |      | ms   |
| T6        | 1000          |      |      | ms   |

#### 4.4.6 LCD Signal Cable Definition

*Table 15 - LCD Signal Definition*

| Pin No. | Symbol | Description          | Pin No. | Symbol | Description         |
|---------|--------|----------------------|---------|--------|---------------------|
| 1       | GND    | Power Ground         | 21      | G5     | Green Data 5 (MSB)  |
| 2       | GND    | Power Ground         | 22      | G4     | Green Data 4        |
| 3       | NC     | No Connect           | 23      | G3     | Green Data 3        |
| 4       | VCC    | Digital Power Supply | 24      | GND    | Power Ground        |
| 5       | VCC    | Digital Power Supply | 25      | G2     | Green Data 2        |
| 6       | VCC    | Digital Power Supply | 26      | G1     | Green Data 1        |
| 7       | VCC    | Digital Power Supply | 27      | G0     | Green Data 0 (LSB)  |
| 8       | NC     | No Connect           | 28      | GND    | Power Ground        |
| 9       | DE     | Data Enable          | 29      | R5     | Red Data 5 (MSB)    |
| 10      | GND    | Power Ground         | 30      | R4     | Red Data 4          |
| 11      | GND    | Power Ground         | 31      | R3     | Red Data 3          |
| 12      | GND    | Power Ground         | 32      | GND    | Power Ground        |
| 13      | B5     | Blue Data 5 (MSB)    | 33      | R2     | Red Data 2          |
| 14      | B4     | Blue Data 4          | 34      | R1     | Red Data 1          |
| 15      | B3     | Blue Data 3          | 35      | R0     | Red Data 0 (LSB)    |
| 16      | GND    | Power Ground         | 36      | GND    | Power Ground        |
| 17      | B2     | Blue Data 2          | 37      | GND    | Power Ground        |
| 18      | B1     | Blue Data 1          | 38      | DCLK   | Clock Signal- Note1 |
| 19      | B0     | Blue Data 0 (LSB)    | 39      | GND    | Power Ground        |
| 20      | GND    | Power Ground         | 40      | GND    | Power Ground        |

*Note1 - Latch Data at the Falling Edge*

##### 4.4.6.1 LCD Signal Mating Cable

Mating FFC is **MT-FP430N-2FR** manufactured by UJU or equivalent. (0.5mm pitch 40 pin FFC)

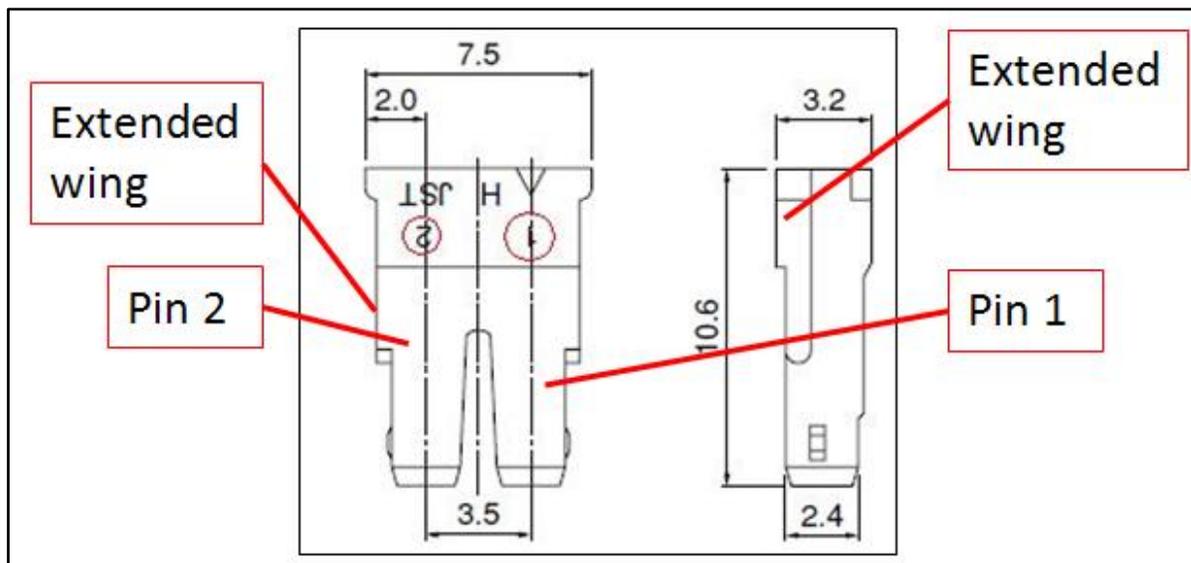
#### 4.4.7 Backlight Signal Cable Definition

**Table 16 - Backlight Signal Definition**

| Pin No. | Symbol | Description        |
|---------|--------|--------------------|
| 1       | VLED+  | Red, LED Anode     |
| 2       | VLED-  | White, LED Cathode |

Note: Backlight socket is **SM02B-BHSS-1-TB** manufactured by JST. The connector on the backlight cable is **BHSR-02VS-1** manufactured by JST.

Backlight pin ordering of the cable attached to the LCD is shown below.



**Figure 7 - Backlight Pin Ordering**

Note: Top of connector has wide wings that extend out.

### 4.5 LCD INTERNAL BLOCK DIAGRAM

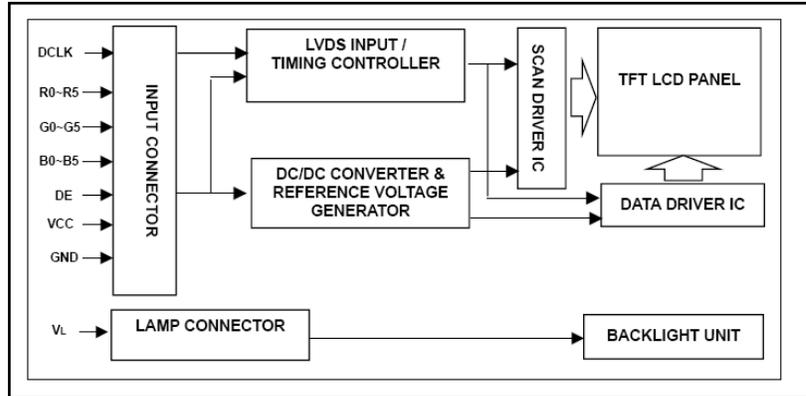


Figure 8 - LCD Block Diagram

### 4.6 OPTICAL PERFORMANCE

Table 17 - LCD Optical Performance

| Parameter          |       | Symbol     | Cond'n                               | Min.  | Typ.  | Max.  | Unit              | Remark            |
|--------------------|-------|------------|--------------------------------------|-------|-------|-------|-------------------|-------------------|
| Brightness         |       | -          | Viewing Normal Angle $\Phi=\theta=0$ | 300   | 350   | -     | cd/m <sup>2</sup> | Center of Display |
| Response Time      |       | Tr         |                                      | -     | 5     | 10    | ms                |                   |
|                    |       | Tf         |                                      | -     | 11    | 16    | ms                |                   |
| Contrast Ratio     |       | CR         |                                      | 250   | 400   |       | -                 |                   |
| Color Chromaticity | White | Wx         | CR <sub>≥</sub> 10                   | 0.249 | 0.299 | 0.349 | -                 |                   |
|                    |       | Wy         |                                      | 0.278 | 0.328 | 0.378 |                   |                   |
| Viewing Angle      | Hor.  | $\theta_R$ |                                      | 60    | 70    |       | Deg               |                   |
|                    |       | $\theta_L$ |                                      | 60    | 70    |       |                   |                   |
|                    | Ver.  | $\Phi_T$   | 50                                   | 60    |       |       |                   |                   |
|                    |       | $\Phi_B$   | 60                                   | 70    |       |       |                   |                   |

Note: Parameters in above table are for LCD only.

## 5 RELIABILITY AND TESTING

### 5.1 RELIABILITY TEST SPECIFICATIONS

*Table 18 - Reliability Test Specifications*

| Item                       | Condition  |
|----------------------------|--|
| High Temperature Storage   | T <sub>A</sub> = +70°C, 240 hrs                      |
| Low Temperature Storage    | T <sub>A</sub> = -30°C, 240 hrs                      |
| High Temperature Operation | T <sub>A</sub> = +60°C, 240 hrs                      |
| Low Temperature Operation  | T <sub>A</sub> = -20°C, 240 hrs                      |
| Thermal Cycling            | -20°C (30 min) · +60°C (30 Min),<br>100 cycles (DRY) |
| Electrostatic Discharge    | ±8kV (Contact) / ±10kV (air)                         |

### 5.2 PACKAGING SPECIFICATIONS

*Table 19 - Packaging Specifications*

| Item                           | Condition   |
|--------------------------------|---|
| Drop Test                      | <ol style="list-style-type: none"> <li>1) Drop Sequence: 1 corner, 3 edges, and 6 surfaces.</li> <li>2) Drop height according to the weight of the package.</li> <li>3) Inspection: sampling check, check each layer of upper and lower, 2 layers in center, total 4 layers.</li> </ol> |
| Non-Operating Random Vibration | <ol style="list-style-type: none"> <li>1) Truck Spectrum: (0.52G rms) and Air Spectrum: (PSD=1.46G rms), 3 axis (X/Y/Z), 20 min per axis per test.</li> <li>2) Inspection: sampling check, check each layer of upper and lower, 2 layers in center, total 4 layers.</li> </ol>          |

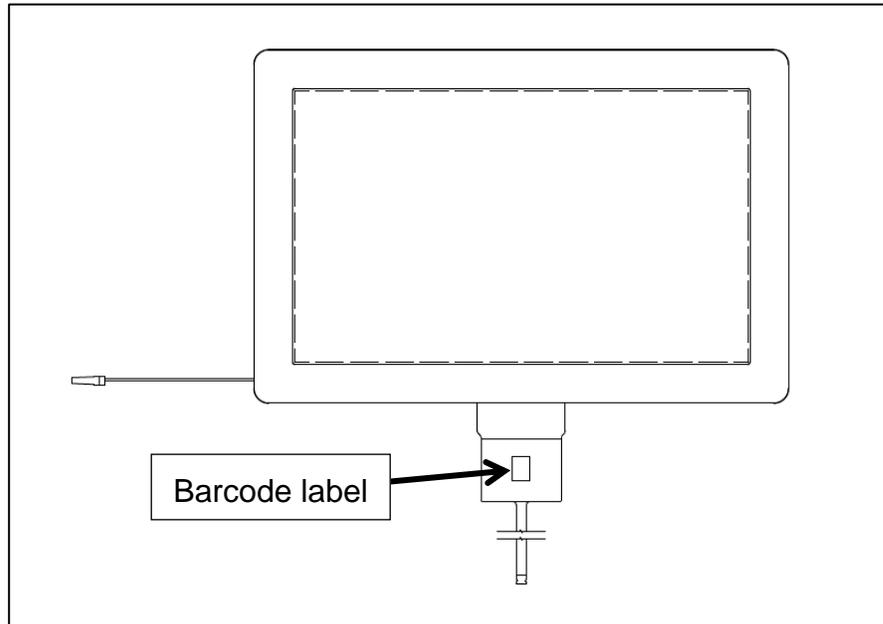
## 6 BARCODE

### 6.1 DESCRIPTION

Every Fusion touch panel contains a unique 2 dimensional barcode. This barcode is used for serial number identification and part specification.

### 6.2 LOCATION

The barcode is located on the flex tail as pictured below.



*Figure 9 – Barcode Label Area (Front View of Module Shown)*

### 6.3 CONTENTS

The barcode contains the serial number, Touch Revolution part number, project name (if applicable), and touch firmware release version.

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## 7 HANDLING AND PRECAUTIONS

### 7.1 DISASSEMBLY OR MODIFICATION

Do not disassemble or modify the touch display. This may cause damage to sensitive components and may cause dust or scratches between the touch sensor and LCD. Touch Revolution's warranty will be void if the unit has been disassembled or modified.

### 7.2 UV EXPOSURE

Long term exposure to sunlight can affect the optical performance of the LCD.

### 7.3 CLEANING

The cover glass should be cleaned using a soft, lint free cloth. It is recommended that either an ammonia based glass cleaner (e.g. Windex) or a 50:50 solution of isopropyl alcohol and water be used for cleaning the sensor. Apply the cleaning solution to the cloth and gently wipe the surface of the sensor. To help minimize streaking, wipe in a circular motion starting in the center and working outwards.

### 7.4 STATIC ELECTRICITY

Since the LCD and Touch panel use CMOS ICs, the device is susceptible to electrostatic discharge. Please use appropriate grounding when handling these modules.

### 7.5 ABSOLUTE MAXIMUM RATINGS

Do not exceed the absolute maximum rating values for the supply voltages and environmental conditions to prevent damage to the touch display.

### 7.6 BREAKAGE

If the LCD panel breaks be careful not to touch any liquid crystal material that may spill. Immediately rinse with water if liquid crystal material comes in contact with skin.

### 7.7 INPUT VOLTAGES

Turn off the power supply before handling and/or inserting signal or power cables to the touch module.

### 7.8 STATIC IMAGES

If fixed images are displayed for a long period of time, an afterimage is likely to occur.

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## 7.9 OUTGASSING

Do not store or use the touch module in an environment where caustic materials such as reagents, solvents, adhesives, and resins are present. Outgassing of these materials can damage the polarizer and ACF connections.

## APPENDIX A

### Note 1: Linearity Test Definition

The linearity of the sensor is tested by dragging a 6mm diameter copper slug in a line across the first surface of the touch sensor. The distance between the actual location of the center of the slug and the reported location shall be less than or equal to the maximum specified error.

### Note 2: Report Rate

Report rate is the maximum rate at which touch data is returned to the host PC. The report rate may drop to 30 interrupts/second for some unique two finger touch combinations.

### Note 3: Response Time

Response time is the time elapsed between first touch and interrupt assuming touch is in active mode

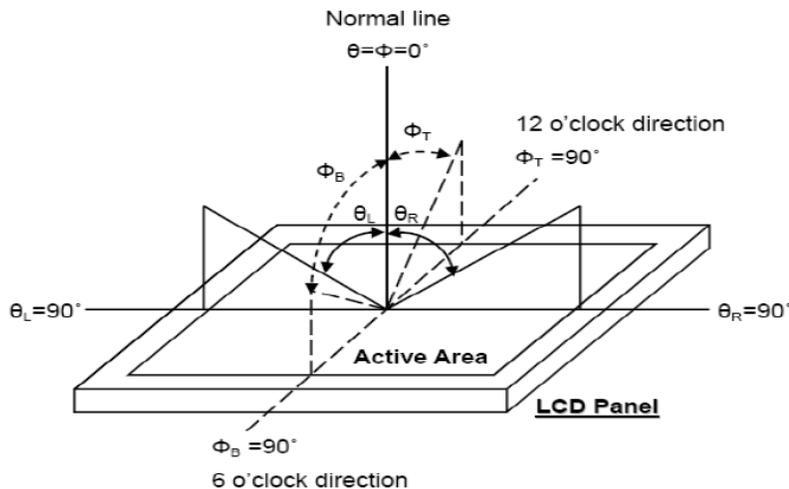
### Note 4: Minimum Touch Diameter

The minimum touch diameter is the minimum diameter of a copper slug that is needed to record a touch.

### Note 5: Optical Transmittance

Measured Per ASTM D1003

### Note 6: Viewing Angle



### Note 7: First Surface Hardness

Measured Per ASTM D3363

# APPENDIX B

