4.5Vdc –14Vdc input; 0.5Vdc to 2.0Vdc output; 80A Output Current



PMBUS

**RoHS Compliant** 

### Applications

- Networking equipment
- Telecommunications equipment
- Servers and storage applications
- Distributed power architectures
- Intermediate bus voltage applications
- Industrial equipment



#### **Features**

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863.
- Compliant to REACH Directive (EC) No 1907/2006
- Compatible in a Pb-free or SnPb reflow environment (Z versions)
- Compliant to IPC-9592 (September 2008), Category 2, Class II
- Wide Input voltage range (4.5Vdc-14Vdc)
- Output voltage programmable from 0.6Vdc to 2.0Vdc via external resistor. Digitally adjustable down to 0.5Vdc output.
- Digital interface through the PMBus<sup>™</sup> # protocol
- Digital Tunable Loop<sup>™</sup> to optimize dynamic output voltage response
- Remote On/Off
- Digital Sequencing
- Power Good signal
- Fixed switching frequency with capability for external synchronization
- Ability to sink and source current
- Output overcurrent protection (non-latching)
- Over temperature protection
- Cost efficient open frame design
- Small size: 33.02mm x 22.86mm x 12.7mm
   [1.3" x 0.9" x 0.5"]
- Wide operating temperature range [-40°C to 85°C]
- ANSI/UL\* 62368-1 and CAN/CSA<sup>+</sup> C22.2 No. 62368-1 Recognized, DIN VDE<sup>‡</sup> 0868-1/A11:2017 (EN62368-1:2014/A11:2017)
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

### Description

The 80A Digital GigaDLynx<sup>™</sup> power modules are non-isolated dc-dc converters that deliver up to 80A of output current. These modules operate over a wide range of input voltage (V<sub>IN</sub> =4.5Vdc - 14Vdc) and provide a precisely regulated output voltage from 0.6Vdc to 2Vdc, programmable via an external resistor and/or PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, over current, over voltage and over temperature protection. The PMBus interface supports many commands to both control and monitor the module. The module also includes the Digital Tunable Loop<sup>™</sup> feature that allows the user to optimize the dynamic response of the converter with reduced amounts of output capacitance leading to savings on cost and PWB area.

\* UL is a registered trademark of Underwriters Laboratories, Inc.

- <sup>+</sup> CSA is a registered trademark of Canadian Standards Association.
- <sup>‡</sup> VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
- \*\* ISO is a registered trademark of the International Organization of Standards

<sup>#</sup> The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Absolute Maximum Ratings**

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the technical requirements. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage	All	VIN	-0.3	15	V
Continuous					
SEQ, ADDR0, ADDR1, RTUNE, VTRACK				2.0	V
VS+	All			3.0	V
ON/OFF				15	V
SYNC, CLK, DATA, SMBALERT#, PGOOD	All			5.5	V
Operating Ambient Temperature	All	TA	-40	85	°C
(see Thermal Considerations section)					
Storage Temperature	All	T <sub>stg</sub>	-55	125	°C

### **Electrical Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

		-		•		
Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V <sub>IN</sub>	4.5	_	14	Vdc
Maximum Input Current	All	I <sub>IN,max</sub>			46	Adc
$(V_{IN}=4.5V \text{ to } 14V, I_0=I_{O, max})$						
Input No Load Current	V <sub>O,set</sub> = 0.6 Vdc	I <sub>IN,No load</sub>		145		mA
( $V_{IN}$ = 12Vdc, $I_0$ = 0, module enabled)	V <sub>o,set</sub> = 2.0Vdc	IIN1No load		190		mA
Input Stand-by Current ( $V_{IN}$ = 12Vdc, module disabled)	All	IN,stand-by		45		mA
Inrush Transient	All	l²t		1		A <sup>2</sup> s
Input Noise on nominal output (VIN=VIN, nom and IO=IO, min to IO,max, Cin = $6 \times 22\mu$ F + $1 \times 470$ uF} Peak-to-Peak (Full Bandwidth)	All				500	mVpp
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1 $\mu$ H source impedance; V <sub>IN</sub> =0 to 14V, I <sub>0</sub> = I <sub>0max</sub> ; See Test Configurations)	All			40		mAp-p
Input Ripple Rejection (120Hz)	All			-55		dB
Output Voltage Set-point (with 0.1% tolerance for external	0 to 70°C	V <sub>O, set</sub>	-0.5		+0.5	% V <sub>O, set</sub>
resistor used to set output voltage)	-40 to +85°C	V O, set	-0.8		+0.8	70 V (), set
Voltage Regulation <sup>1</sup>						
Line Regulation	(V <sub>IN</sub> =V <sub>IN, min</sub> to V <sub>IN, max</sub> )			3		mV
Load (Io=Io, min to Io, max) Regulation	All			3		mV

<sup>1</sup>Worst case Line and load regulation data, all temperatures, from design verification testing as per IPC9592.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Adjustment Range (selected by an external resistor) (Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section)	All	Vout	0.6		2.0	Vdc
PMBus Adjustable Output Voltage Range	All	$V_{O,adj}$	0.5	-	2.0	Vdc
PMBus Output Voltage Adjustment Step Size	All			0.233		%V <sub>0,set</sub>
Remote Sense Range	All				0.4	Vdc
Output Ripple and Noise on nominal output $(V_{IN}=V_{IN,nom} \text{ and } I_0=I_{0,min} \text{ to } I_{0,max} \text{ Co} = 6 \text{ x } 47 \mu\text{F} + 4 \text{ x } 0.1 \mu\text{F},$ Cin = 6 x 22 $\mu$ F + 1 x 470 $\mu$ F						
Peak-to-Peak (Full bandwidth)					30	$mV_{pk\text{-}pk}$
RMS (Full bandwidth)	All				12	mV <sub>rms</sub>
External Capacitance						
Minimum output capacitance (ESR $\geq$ 3 m $\Omega$ )	All	C <sub>O,min</sub>	470	_		μF
Maximum output capacitance (ESR $\geq$ 3 m $\Omega$ )	All	C <sub>O</sub> , max		_	16000	μF
Output Current (in either sink or source mode)	All	l <sub>o</sub>	0		80	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	Io, lim		91		Adc
Output Short-Circuit Current	All	I <sub>O, s/c</sub>		14.6		Arms
(V₀≤260mV) (Hiccup Mode )						
Efficiency	V <sub>0,set</sub> = 0.6Vdc	η		82.4		%
V <sub>IN</sub> = 12Vdc, T <sub>A</sub> =25°C	V <sub>O, set</sub> = 0.8Vdc	η		85.7		%
I <sub>O</sub> =I <sub>O, max</sub> , V <sub>O</sub> = V <sub>O,set</sub>	V <sub>o,set</sub> = 1.0Vdc	η		88.1		%
	V <sub>0,set</sub> = 1.2Vdc	η		89.6		%
	V <sub>O, set</sub> = 1.5Vdc	η		91.2		%
	V <sub>0,set</sub> = 2.0Vdc	η		92.8		%
Switching Frequency	All	f <sub>sw</sub>	-	400	-	kHz
Frequency Synchronization	All			I		
Synchronization Frequency Range	All		-10		+10	%
High-Level Input Voltage	All	VIH, SYNC	2.0			v
Low-Level Input Voltage	All	VIL,SYNC			0.4	v
Minimum Pulse Width, SYNC	All	t <sub>sync</sub>	50			ns

### **General Specifications**

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I_0=0.8I_{0, max}, T_A=40°C) Telecordia Issue 3 Method 1 Case 3	All		39,165,215		Hours
Weight			22.5(0.793)	—	g (oz.)

Data Sheet

# 80A GigaDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Feature Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
$(V_{\text{IN}}{=}V_{\text{IN},\text{min}}$ to $V_{\text{IN},\text{max}}$ ; open collector or equivalent,						
Signal referenced to GND)						
Device Code with no suffix - Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
Input High Current	All	Ін	_	_	1	mA
Input High Voltage	All	Vін	2	_	V <sub>IN, max</sub>	Vdc
Logic Low (Module ON)						
Input low Current	All	١ı	_	_	10	μA
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Device Code with suffix "4" - Positive Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module ON)						
Input High Current	All	Ін	_	_	10	uA
Input High Voltage	All	Vih	2	_	V <sub>IN, max</sub>	Vdc
Logic Low (Module OFF)	/	•	-		• IIV, IIIdX	vac
Input low Current	All	lı.	_	_	300	μA
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Turn-On Delay and Rise Times		VIL	-0.2		0.4	Vuc
$(V_{IN}=V_{IN, nom, lo=l_{0, max}}, V_0$ to within ±1% of steady state) Case 1: On/Off input is enabled and then input power is applied (delay from						
instant at which $V_{IN} = V_{IN, min}$ until $V_0 = 10\%$ of $V_0$ , set)	All	Tdelay	—	5.0	-	ms
Case 2: Input power is applied for at least one second and then the On/Off						
input is enabled (delay from instant at which Von/Off is enabled until $V_0 = 100($ of $V_0 = 100($	All	Tdelay	_	500	-	μs
10% of V <sub>o, set</sub> ) Output voltage Rise time (time for V <sub>0</sub> to rise from 10% of Vo, set to 90% of						
Vo, set)	All	Trise	—	2.0	-	msec
Output voltage overshoot ( $T_A = 25^{\circ}C V_{IN} = V_{IN, min}$ to $V_{IN, max}$ , $I_0 = I_{0, min}$ to $I_{0, max}$ )		Output			3.0	% V <sub>0, set</sub>
With or without maximum external capacitance		Output			5.0	70 V 0, set
Over Temperature Protection (See Thermal Considerations section)	Vin ≤ 6.5V	- T <sub>ref</sub>		105		°C
	Vin > 6.5V			125		
PMBus Over Temperature Warning Threshold*	Vin ≤ 6.5V	TWARN		95		°C
	Vin > 6.5V			115		
Tracking Accuracy ( $V_{IN, min}$ to $V_{IN, max}$ ; $I_{O, min}$ to $I_{O, max}$ VSEQ < Vo)						
(Power-Up: 0.5V/ms)	All	Vseq –Vo			100	mV
(Power-Down: 0.5V/ms)	All	Vseq –Vo			100	mV
Input Undervoltage Lockout						
Turn-on Threshold	All				4.5	Vdc
Turn-off Threshold	All		4.1			Vdc
Hysteresis	All			0.25		Vdc
PMBus Adjustable Input Under Voltage Lockout Thresholds	All		4.5		14	Vdc
Resolution of Adjustable Input Under Voltage Threshold	All				10	mV

\* Over temperature Warning – Warning may not activate before alarm and unit may shut down before warning.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Feature Specifications (cont.)**

Parameter	Device	Symbol	Min	Тур	Max	Units
PGOOD (Power Good)						
Signal Interface, $V_{supply} \le 5VDC$						
Overvoltage threshold for PGOOD ON	All			108		%V <sub>O, set</sub>
Overvoltage threshold for PGOOD OFF	All			110		%V <sub>O, set</sub>
Undervoltage threshold for PGOOD ON	All			92		%V <sub>O, set</sub>
Undervoltage threshold for PGOOD OFF	All			90		%V <sub>O, set</sub>
Sink/source current capability into PGOOD pin	All				2	mA

\* Over temperature Warning – Warning may not activate before alarm and unit may shut down before warning.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Digital Interface Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						
Input High Voltage (CLK, DATA)		Vін	2.0			V
Input Low Voltage (CLK, DATA)		VIL			0.8	V
Output current – low (CLK, DATA, SMBALERT#)		IOL			2	mA
PMBus Operating frequency range	Slave Mode	Fpmb	10	400	500	kHz
Data hold time		thd:dat	300			ns
Data setup time		tsu:dat	100			ns
Clock low time-out		t <sub>timeout</sub>		25	35	ms
Clock low period		t <sub>LOW</sub>	1.3			μs
Clock high period		t <sub>HIGH</sub>	0.6			μs
Clock or data fall time		t <sub>F</sub>			300	ns
Clock or data fall time		t <sub>R</sub>			300	ns
Internal Pull-up resistors on DATA, CLK and SMBALRT pins				50K		Ω
Measurement System Characteristics						
Read delay time		tdly	153	192	231	μs
Output current measurement range		I <sub>RNG</sub>	0		100	А
Output current measurement resolution		Ires		197		mA
Output current measurement gain accuracy	0°C to 85°C	I <sub>ACC</sub>			±5	% of Io,max
	-40°C to +85°C	IACC	-3		+7	Α
Output current measurement offset		I <sub>OFST</sub>		0.2		А
V <sub>OUT</sub> measurement range		V <sub>OUT</sub>	0.5		2.0	V
V <sub>OUT</sub> measurement resolution		V <sub>OUT(res)</sub>		0.7		mV
V <sub>OUT</sub> measurement accuracy		V <sub>OUT(gain)</sub>		±1		%
Vout measurement offset		V <sub>OUT(ofst)</sub>	-5		5	mV
V <sub>IN</sub> measurement range		V <sub>IN(rng)</sub>	0		14	V
V <sub>IN</sub> measurement resolution		V <sub>IN(res)</sub>		7.0		mV
V <sub>IN</sub> measurement accuracy		V <sub>IN</sub>		±1		%

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

The following figures provide typical characteristics for the 80A Digital GigaDLynx<sup>™</sup> at 0.6Vo and 25°C.



Figure 1. Converter Efficiency versus Output Current.



TIME, t (1µs/div)

Figure 3. Typical output ripple and noise (C<sub>0</sub>=  $6x47\mu$ F ceramic, V<sub>IN</sub> = 12V, I<sub>0</sub> = I<sub>0,max</sub>).



Figure 5. Typical Start-up Using On/Off Voltage (Io = Io,max).



Figure 2. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)





TIME, t (2ms/div)

Figure 6. Typical Start-up Using Input Voltage (VIN = 12V,  $I_{0}$  =  $I_{0,max}$  ).

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

The following figures provide typical characteristics for the 80A GigaDLynx<sup>™</sup> at 1.0Vo and 25°C







TIME, t (1µs/div)

Figure 9. Typical output ripple and noise ( $C_0$ = 6x47µF Ceramic,  $V_{IN}$  = 12V,  $I_0$  =  $I_{0,max}$ .).



(Zms/uiv)





Figure 8. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)

Figure 10. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 30x 47 $\mu$ F + 11x 1000 $\mu$ F, R<sub>TUNE</sub> = 3.74k $\Omega$ 



Figure 12. Typical Start-up Using Input Voltage (VIN = 12V, I₀ = I₀,max).

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

The following figures provide typical characteristics for the 80A Digital GigaDLynx<sup>™</sup> at 1.2Vo and 25°C.







TIME, t (1µs/div)









Figure 14. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)

Figure 16. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 26x 47 $\mu$ F + 9x 1000 $\mu$ F, R<sub>TUNE</sub> = 3.24k $\Omega$ 



Figure 18. Typical Start-up Using Input Voltage (VIN = 12V, I₀ = I₀,max).

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

The following figures provide typical characteristics for the 80A Digital GigaDLynx<sup>™</sup> at 1.5Vo and 25°C.







TIME, t (1µs/div)

Figure 21. Typical output ripple and noise ( $C_0$ = 6x47µF ceramic, VIN = 12V, I<sub>0</sub> = I<sub>0,max</sub>, ).



TIME, t (2ms/div)

Figure 23. Typical Start-up Using On/Off Voltage (Io = Io,max).



Figure 20. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)

Figure 22. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 25x 47 $\mu$ F + 8x 1000 $\mu$ F, R<sub>TUNE</sub> = 6.81k $\Omega$ 



#### TIME, t (2ms/div)



4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

The following figures provide typical characteristics for the 80A Digital GigaDLynx<sup>™</sup> at 2.0Vo and 25°C.



Figure 25. Converter Efficiency versus Output Current.



TIME, t (1µs/div)

Figure 27. Typical output ripple and noise ( $C_0$ = 6x47µF ceramic, VIN = 12V, Io = Io,max, ).







Figure 26. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)

Figure 28. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 20x 47 $\mu$ F + 7x 1000 $\mu$ F, R<sub>TUNE</sub> = 6.04K $\Omega$ 



TIME, t (2ms/div)

Figure 30. Typical Start-up Using Input Voltage ( $V_{IN}$  = 12V,  $I_0$  =  $I_{0,max}$ ).

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Design Considerations**

#### **Input Filtering**

The 80A GigaDLynx<sup>™</sup> module must be powered from a lowimpedance source. An inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pins of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 31 shows the input ripple voltage for various output voltages at 80A of load current with  $6x22 \ \mu\text{F} + 3x0.1 \ \mu\text{F} + 1x470 \ \mu\text{F}$  OSCON electrolytic capacitor at an input of 12V.



# Figure 31. Input ripple voltage for various output voltages with (3 x $0.1\mu$ F + 6 x 22 $\mu$ F) ceramic + 1 x 470 $\mu$ F OSCON electrolytic capacitor at the input (80A load). Input voltage is 12V.

#### **Output Filtering**

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with minimum of  $6x47\mu$ F ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module.



Figure 32. Output ripple voltage for various output voltages with external 6 x 47 $\mu$ F + 4 x 0.1  $\mu$ F + 2 x 4.7nF ceramic capacitors at the output (80A load). Input voltage is 12V.

### Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL ANSI/UL\* 62368-1 and CAN/CSA+ C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/A11:2017 (EN62368-1:2014/A11:2017.

For the converter output to be considered meeting the Requirements of safety extra-low voltage (SELV) or ES1, the input must meet SELV/ES1 requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

For input voltages greater than 7V, single external 40A 465 Series Fast Acting Littelfuse fuse on the ungrounded input pin is recommended. For input voltages less than 7V, two 30A 678 Series Bel Fast Acting Fuses in parallel is recommended.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Analog Feature Descriptions**

#### Remote On/Off

The GigaDLynx 80A module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the ON/OFF input:

- Module ON/OFF is controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF is controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF is controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

#### Analog On/Off

The 80A GigaDLynx<sup>™</sup> power modules feature an On/Off pin for remote On/Off operation. With the Negative Logic On/Off option, (see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. Leaving the On/Off pin disconnected will turn the module ON when input voltage is present. With the positive logic on/off option, the module turns ON during logic high and OFF during logic low.

#### **Digital On/Off**

#### Please see the Digital Feature Descriptions section.

#### **Monotonic Start-up and Shutdown**

The module has monotonic start-up and shutdown behavior on the output voltage for any rated input voltage, output voltage and current, and operating temperature.

#### Startup considerations at Low Temperature.

GDT080 is able to handle specified full-load start-up for ambient temperatures above or equal to -10°C. Below -10°C ambient temperature, the load has to be limited to 75% of specified full-load.

#### **Startup into Pre-biased Output**

The module can start into a pre-biased output as long as the pre-bias voltage is 0.5V less than the set output voltage.

#### **Analog Output Voltage Programming**

The output voltage of the module is programmable to any voltage from 0.6 to 2.0 Vdc by connecting a resistor between the Trim and VS- pins of the module as shown in Fig 33.

Without an external resistor between the Trim and VS- pins, the output of the module will be 0.6 Vdc. The value of the trim resistor,  $R_{TRIM}$  for a desired output voltage, should be selected as per the following equation:



Figure 33. Circuit configuration for programming output voltage using an external resistor.

 $R_{TRIM}$  is the external resistor in k $\Omega$ 

Vout is the desired output voltage.

Vref = 0.6V

Table 1 provides Rtrim values required for some common output voltages.

#### Table 1

V <sub>O, set</sub> (V)	R <sub>TRIM</sub> <i>(</i> KΩ)
0.6	Open
0.8	6.0
1.0	3.0
1.2	2.0
1.5	1.33
2.0	0.866

### Digital Output Voltage Adjustment

#### Please see the Digital Feature Descriptions section.

#### **Remote Sense**

The power module has a differential Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.4V.

#### **Output Voltage Sequencing**

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. This pin is disabled as a factory default setting, **if using this feature it should be enabled using the MFR\_FEATURES\_CONTROL (E7h) command**. When not using the sequencing feature, leave it unconnected and leave the default setting unchanged.

The voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown in Fig 34. In addition, a small capacitor (suggested value 100pF) should be connected across the lower resistor R1.

For all DLynx modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is 10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.



# Figure 34. Circuit showing connection of the sequencing signal to the SEQ pin.

When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their set-point voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

#### **Digital Compensator**

The GDT080 module uses digital control to regulate the output voltage. As with all POL modules, external capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 32 for example data) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable. In the GDT080, using a feature called the Digital Tunable Loop<sup>™</sup>, the digital compensation can be adjusted externally to optimize transient response and also ensure stability for a wide range of external capacitance, as well as with different types of output capacitance. This is done by allowing the user to select among several pre-tuned compensation choices to select the one most suited to the transient response needs of the load. Figure 35 shows how the resistor RTune is connected between the RTUNE and GND pins to select the appropriate pre-tuned compensation.



# Figure 35. Circuit diagram showing connection of $R_{\text{TUNE}}$ to tune the control loop of the module.

Recommended values of  $R_{TUNE}$  for different output capacitor combinations are given in Table 2. The GDT080 pre-tuned compensation can be divided into four different banks (COMP0, COMP1, COMP2 and COMP3) that are available to the user to compensate the control loop for various values and combinations of output capacitance and to obtain reliable and stable performance under different conditions. Each bank consists of seven different sets of compensation coefficients pre-calculated for different values of output capacitance. The four banks are set up as follows:

- COMP0: Recommended for the case where all of the output capacitance is composed of only ceramic capacitors. The range of external output capacitance is from the required minimum value of 470µF to a maximum of 7500µF.
- COMP1: For the most commonly used mix of ceramic and polymer type capacitors that have higher output capacitance in a smaller size and for output voltages between 0.6V to 1.2V. The range of output capacitance is from 470 $\mu$ F to a maximum of 15,692 $\mu$ F. This is the combination of output capacitance and compensation that can achieve the best transient response at lowest cost and smallest size. For example, with the maximum output capacitance of 15,692 $\mu$ F, and selecting RTUNE = 4.22 $k\Omega$ , transient deviation can be as low as 15mV, for a 50% load step (0 to 40A).
- COMP2: Same range and types of capacitance as COMP1, but for an output voltage range from 1.2V to 2V.
- COMP3: Suitable also for a mix of ceramic and higher ESR polymers or electrolytic capacitors such as OSCON.

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Selecting R<sub>TUNE</sub> according to Table 2 will ensure stable operation of the module with sufficient stability margin as well as yield

optimal transient response.

Output Capacitance	Number of Output Capacitors**	Total Output Capacitance (μF)**	Compensation Bank	R <sub>TUNE</sub> resistor (kΩ)
Туре				-
Ceramic	18 x 47µ	846	Comp 0	0
Ceramic	18 x 47μ + 9 x 100μ	1746	Comp 0	0.392
Ceramic	18 x 47µ + 16 x 100µ	2446	Comp 0	0.576
Ceramic	18 x 47μ + 22 x 100μ	3046	Comp 0	0.787
Ceramic	18 x 47μ + 40 x 100μ	4846	Comp 0	1
Ceramic	18 x 47μ + 52 x 100μ	6046	Comp 0	1.24
Ceramic	18 x 47µ + 83 x 100µ	9146	Comp 0	1.5
Ceramic + Polymer	16 x 47μ + 2 x 1000μ	2752	Comp 1	1.78
Ceramic + Polymer	16 x 47μ + 3 x 1000μ	3752	Comp 1	2.1
Ceramic + Polymer	16 x 47μ + 5 x 1000μ	5752	Comp 1	2.43
Ceramic + Polymer	16 x 47μ + 7 x 1000μ	7752	Comp 1	2.8
Ceramic + Polymer	16 x 47μ + 9 x 1000μ	9752	Comp 1	3.24
Ceramic + Polymer	18 x 47μ + 12 x 1000μ	12,486	Comp 1	3.74
Ceramic + Polymer	18 x 47μ + 14 x 1000μ	14,846	Comp 1	4.22
Ceramic + Polymer	16 x 47μ + 2 x 1000μ	2752	Comp 2	4.75
Ceramic + Polymer	16 x 47μ + 3 x 1000μ	3752	Comp 2	5.36
Ceramic + Polymer	16 x 47μ + 5 x 1000μ	5752	Comp 2	6.04
Ceramic + Polymer	16 x 47μ + 7 x 1000μ	7752	Comp 2	6.81
Ceramic + Polymer	16 x 47μ + 9 x 1000μ	9752	Comp 2	7.68
Ceramic + Polymer	18 x 47μ + 12 x 1000μ	12,846	Comp 2	8.66
Ceramic + Polymer	18 x 47μ + 14 x 1000μ	14,846	Comp 2	9.53
Ceramic + Electrolytic	16 x 47μ + 4 x 470μ	2632	Comp 3	10.5
Ceramic + Electrolytic	16 x 47μ + 7 x 470μ	4042	Comp 3	11.8
Ceramic + Electrolytic	16 x 47μ + 9 x 470μ	4982	Comp 3	13
Ceramic + Electrolytic	18 x 47μ + 14 x 470μ	7246	Comp 3	14.3
Ceramic + Electrolytic	18 x 47μ + 20 x 470μ	10,246	Comp 3	15.8
Ceramic + Electrolytic	18 x 47μ + 24 x 470μ	12,126	Comp 3	17.4
Ceramic + Electrolytic	18 x 47μ + 30 x 470μ	14,946	Comp 3	19.1

#### Table 2. Recommended R<sub>TUNE</sub> Compensation

\*\* Total output capacitance includes the capacitance inside the module of value 8 x 47μF (3mΩ ESR).

Note: The capacitors used in the digital compensation Loop tables are  $47\mu F/3 m\Omega$  ESR ceramic,  $100uF/3.2m\Omega$  ceramic,  $1000 \mu F/6m\Omega$  ESR polymer capacitor and  $470uF/9m\Omega$  ESR Polymer capacitor.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of  $R_{TUNE}$  in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 40A to 80A step change (50% of full load), with an input voltage of 12V.

Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external RTUNE to tune the module for best transient performance and stable operation for other output capacitance values. Simulation models are also available via the GE Power Module Wizard to predict stability characteristics and transient response.

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# Table 3. Recommended values of $R_{TUNE}$ to obtain transient deviation of 2% of Vout for a 40A step load with Vin=12V.

Vo	2V	1.2V	0.6V
	14x47uF +	28x47uF +	36x47uF +
Co	5x1000µF	9x1000µF	14x1000µF
	polymer	polymer	polymer
R <sub>TUNE</sub> (kΩ)	9.53	3.24	4.22
ΔV (mV)	32	19.8	12

#### Power Module Wizard

GE offers a free web based easy to use tool that helps users simulate the Tunable Loop performance of the GDT080. Go to <u>http://ge.transim.com/pmd/Home</u> and sign up for a free account and use the module selector tool. The tool also offers downloadable Simplis/Simetrix models that can be used to assess transient performance, module stability, etc.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

#### **Digital Output Voltage Margining**

#### Please see the Digital Feature Descriptions section.

#### **Overcurrent Protection (OCP)**

To provide protection in a fault (output overload) condition, the unit has internal current-limiting circuitry on the output and can endure current limiting continuously. The module overcurrent response is non-latching shutdown with automatic recovery. The Overcurrent Protection response time is programmable via the PMBus through manufacturerspecific commands. The unit operates normally once the output current is brought back into its specified range.

#### **Load Transient Considerations**

The GDT080 module can achieve 100% load transient above - 10°C ambient temperature. Below -10°C ambient temperature, the load transient is limited to a maximum of 75% of specified full load current.

#### **Digital Sequencing**

The module supports digital sequencing operation. Both ratiometric and simultaneous sequencing are supported.

#### **Overtemperature Protection**

To provide protection in a fault condition, the unit has a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 125°C (typ) is exceeded at the thermal reference point  $T_{ref}$ . Once the unit goes into thermal shutdown it will wait to cool before attempting to restart. The overtemperature threshold is dependent on input voltage, with the 125°C value applicable for input voltages > 6.5V and is changed to 105°C for input voltages ≤ 6.5V.

#### **Digital Temperature Status via PMBus**

#### Please see the Digital Feature Descriptions section.

# Digitally Adjustable Output Over and Under Voltage Protection

#### Please see the Digital Feature Descriptions section.

#### Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

#### **Digitally Adjustable Input Undervoltage Lockout**

#### Please see the Digital Feature Descriptions section.

#### **Digitally Adjustable Power Good Thresholds**

#### Please see the Digital Feature Descriptions section.

#### **Power Good**

The module provides a Power Good (PGOOD) signal that goes high to indicate output voltage being within a specified range. The signal is implemented as push-pull circuit with an internal pull-up resistor of 20K to 3.3V. The PGOOD signal is deasserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The default PGOOD thresholds are ± 15%.

The PGOOD terminal should be connected through a pullup resistor (suggested value 100K  $\!\Omega)$  to a source of 5VDC or lower.

#### Synchronization

The module switching frequency can be synchronized to an external signal within the specified range. Synchronization is done by applying the external signal to the SYNC pin of the module as shown in Fig. 36, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If using this feature it should be enabled using the MFR\_FEATURES\_CONTROL (E7h) command. If the SYNC pin is not used, leave the default setting unchanged and the module runs at the default switching frequency.



Figure 36. External source connections to synchronize switching frequency of the module.

# Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Digital Feature Descriptions**

#### **PMBus Interface Capability**

The 80A Digital GigaDLynx<sup>™</sup> power modules have a PMBus interface that supports both communication and control. The modules supports a subset of version 1.1 of the PMBus specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

All communication over the module PMBus interface will work with or without Packet Error Checking (PEC) . The module generates the correct PEC byte for all transactions, and checks the PEC byte if sent by the master.

The module also supports the SMBALERT# response protocol whereby the module alerts the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored are saved (see Table 6 for which command parameters can be saved in non-volatile storage).

#### **PMBus Data Format**

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by

Value = Mantissa x 2 Exponent

#### **PMBus Addressing**

The power module is addressed through the PMBus using a device address. The module supports 128 possible addresses (0 to 127 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG\_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specification and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (E96 series resistor value is

outside the range specified in Table 4, the module will respond to address 127.

	Table 4							
	PMBus Address Table							
			ADDR	1 Res	istor \	/alues	;	
ADDR0 Resistor Values	0	680	1.2K	1.8K	2.7K	3.9K	4.7K	5.6K
0	64	16	32	48	64	80	96	112
680	1	17	33	49	65	81	97	113
1.2K	2	18	34	50	66	82	98	114
1.8K	3	19	35	51	67	83	99	115
2.7K	4	20	36	52	68	84	100	116
3.9K	5	21	37	53	69	85	101	117
4.7K	6	22	38	54	70	86	102	118
5.6K	7	23	39	55	71	87	103	119
6.8K	8	24	40	56	72	88	104	120
8.2K	9	25	41	57	73	89	105	121
10K	10	26	42	58	74	90	106	122
12K	11	27	43	59	75	91	107	123
15K	12	28	44	60	76	92	108	124
18K	13	29	45	61	77	93	109	125
22К	14	30	46	62	78	94	110	126
27К	15	31	47	63	79	95	111	127

Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2.



Figure 37. Circuit showing connection of resistors used to set the PMBus address of the module.

#### **PMBus Enabled On/Off**

The output of the module can be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON\_OFF\_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

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4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

0 :	Output is disabled
-----	--------------------

1 : Output is enabled

This module uses the lower five bits of the ON\_OFF\_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r/w	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	0

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Action
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit isused together with the CMD, PU and ON bits to determine startup.

Bit Value	Action
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit

#### **PMBus Adjustable Soft Start Rise Time**

The soft start rise time of module output is adjustable in the module via PMBus. The TON\_RISE command can set the rise time in ms, and allows choosing soft start times between 200µs and 14ms.

#### **Output Voltage Adjustment Using the PMBus**

The VOUT\_SCALE\_MONITOR parameter is important for a number of PMBus commands related to output voltage trimming, margining, over/under voltage protection and the PGOOD thresholds. The output voltage of the module is determined by the value of the  $R_{Trim}$  resistor connected between TRIM pin and analog ground VS-, as specified earlier in the data sheet. The information on the output voltage

divider ratio is conveyed to the module through the VOUT\_SCALE\_MONITOR parameter. The read-out of output voltage also depends on VOUT\_SCALE\_MONITOR. If the correct VOUT\_SCALE\_MONITOR is not used, the output voltage read-out will be wrong. The VOUT\_SCALE\_MONITOR parameter is defined by the ratio of internal reference of the controller to the nominal output voltage selected by R<sub>Trim</sub> resistor.

 $VOUT\_SCALE\_MONITOR = \frac{0.6V}{Nominal Output Voltage}$ 

For example, for a nominal output voltage of 1.2V, the VOUT\_SCALE\_MONITOR is equal to 0.5. Table 5 below defines values of VOUT\_SCALE\_MONITOR to the various nominal output voltages.

Table 5

V <sub>O, set</sub> (V)	VOUT_SCALE_MONITOR		
0.6	1		
0.8	0.75		
1.0	0.6		
1.2	0.5		
1.5	0.4		
2.0	0.3		

When PMBus commands are used to trim or margin the output voltage, the value of  $V_{\text{REF}}$  is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module is adjustable with a minimum step size of 1.406mV over a ± 25% range from nominal using the VOUT\_TRIM command over the PMBus.

#### **Output Voltage Margining Using the PMBus**

Output voltage of the module can also be margined via PMBus commands. The command VOUT\_MARGIN\_HIGH sets the margin high voltage, while the command VOUT\_MARGIN\_LOW sets the margin low voltage. Both the VOUT\_MARGIN\_HIGH and VOUT\_MARGIN\_LOW commands use the "Linear" mode. Two bytes are used for data. The actual margined output voltage is determined by the resistor on the TRIM, which as explained earlier is taken into consideration by VOUT\_SCALE\_MONITOR command. The module then sets the output voltage to the margined high or low voltage levels using the OPERATION command. Bits [7:4] are used to enable margining as follows:

1001: Vout set to VOUT\_MARGIN\_LOW (Ignore Fault) 1010: Vout set to VOUT\_MARGIN\_HIGH (Ignore Fault)

#### **Temperature Status via PMBus**

The module provides information related to temperature of the module through standardized PMBus commands. Commands READ\_TEMPERATURE1, READ\_TEMPERATURE\_2 are mapped to module temperature and internal temperature of the PWM controller, respectively. The temperature readings are returned in °C and are two bytes.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# PMBus Adjustable Output Over and Under Voltage Protection

The module has output over and under voltage protection capability. The PMBus command VOUT\_OV\_FAULT\_LIMIT is used to set the output over voltage threshold. The default value is configured to be 115% of the commanded output. The command VOUT\_UV\_FAULT\_LIMIT sets the threshold that detects an output under voltage fault. The default values are 85% of the commanded output voltage. Both commands use two data bytes formatted in the Linear format.

#### PMBus Adjustable Input Undervoltage Lockout

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN\_ON allows setting the input voltage turn on threshold, while the VIN\_OFF command sets the input voltage turn off threshold. For both the VIN\_ON and VIN\_OFF commands, possible values are 4.5V to 14V . Both VIN\_ON and VIN\_OFF commands use the "Linear" format with two data bytes.

#### Measurement of Output Current, Output Voltage, Input Voltage and output power

The module can measure key module parameters such as output current, output voltage and input voltage and provide this information through the PMBus interface.

#### **Measuring Output Current Using the PMBus**

The module measures output current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then multiplied by the current gain factor that will be used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT\_CAL\_GAIN command, and consists of two bytes in the Linear data format. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT\_CAL\_OFFSET command is used to store and read the current offset. The READ\_IOUT command provides tmodule average output current information. This command only supports positive output current, i.e. current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ\_IOUT command returns two bytes of data in the Linear data format.

#### **Measuring Output Voltage Using the PMBus**

The module provides output voltage information using the READ\_VOUT command. The command returns two bytes of data in Linear format

#### **Measuring Input Voltage Using the PMBus**

The module provides input voltage information using the READ\_VIN command. The command returns two bytes of data in the Linear format.

Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. A 1 in the bit position indicates the fault that is flagged.

STATUS\_BYTE : Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	Default Value
7	Х	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

Low Puto
summary of the module's fault/warning conditions.
STATUS_WORD : Returns two bytes of information with a

Bit Position	Flag	Default Value
7	Х	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

#### **High Byte**

Bit Position	Flag	Default Value
7	VOUT fault or warning	0
6	IOUT fault	0
5	VIN Fault	0
4	Х	0
3	PowerGOOD	0
2	Fan Fault	0
1	Shortciruit	0
0	Х	0

STATUS\_VOUT : Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	Х	0
5	Х	0
4	VOUT UV Fault	0
3	Х	0
2	Х	0
1	Х	0
0	Х	0

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

STATUS\_IOUT : Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	Х	0
5	Х	0
4	Х	0
3	Х	0
2	Х	0
1	Х	0
0	Х	0

STATUS\_INPUT : Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VIN_OV_FAULT	0
6	Х	0
5	Х	0
4	VIN_UV_FAULT	0
3	Х	0
2	Х	0
1	Х	0
0	Х	0

STATUS\_TEMPERATURE : Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	Х	0
4	Х	0
3	Х	0
2	Х	0
1	Х	0
0	Х	0

STATUS\_CML : Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported data	0
5	Packet Error Check Failed	0
4	Memory Fault	0
3	х	0
2	Х	0
1	Х	0
0	Х	0

MFR\_VIN\_MIN : Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

MFR\_VOUT\_MIN : Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format – fixed at 614)

MFR\_SPECIFIC\_00 : Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (xxxxxx corresponds to the PLX002 series of module), while bits [7:3] indicate the revision number of the module.

	Low Byte							
Bit Position	Flag							
7:2	Module Name	XXXXXX						
1:0	Reserved	10						

	High Byte	
Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	000

### Writing to OTP (One Time Programmable) Memory

The GDT080 EEPROM memory can be completely written in entirety, for example, using STORE\_DEFAULT\_ALL command, only four times. During the situation of partial rewrites, for example, when trying to store only four commands using STORE\_DEFAULT\_CODE command four times in succession, numerous writes are possible within the confines of available memory.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Summary of Supported PMBus Commands**

Please refer to the PMBus 1.2 specification for more details of these commands. **Table 6** 

Hex Non-Volatile **Brief Description** Command Code Memory Storage Turn Module on or off. Also used to margin the output voltage Format Unsigned Binary **Bit Position** 0 7 6 5 4 3 2 1 01 **OPERATION** Access r/w r/w r/w r/w r/w r r r Function х Х On Margin Х Default Value 0 0 0 0 0 х х 0 Configures the ON/OFF functionality as a combination of analog ON/OFF pin and PMBus commands Format Unsigned Binary **Bit Position** 02 ON OFF CONFIG 7 6 5 4 3 2 1 0 YES Access r r r/w r/w r/w r/w r r Function х х х pol cmd сра pu cpr **Default Value** 0 0 0 1 0 Clear any fault bits that may have been set, also releases the SMBALERT# signal if the device 03 CLEAR\_FAULTS has been asserting it. Used to control writing to the module via PMBus. Copies the current register setting in the module whose command code matches the value in the data byte into non-volatile memory (EEPROM) on the module Format Unsigned Binary **Bit Position** 6 5 0 7 4 3 2 1 Access r/w r/w r/w х х х х х Function bit7 bit6 bit5 х х Х Х Х **Default Value** 0 0 0 Х Х Х Х Х 10 WRITE\_PROTECT YES Bit5: 0 – Enables all writes as permitted in bit6 or bit7 1 - Disables all writes except the WRITE\_PROTECT, OPERATION and ON\_OFF\_CONFIG (bit 6 and bit7 must be 0) Bit 6: 0 - Enables all writes as permitted in bit5 or bit7 1 – Disables all writes except for the WRITE PROTECT and OPERATION commands (bit5 and bit7 must be 0) Bit7: 0 – Enables all writes as permitted in bit5 or bit6 1 – Disables all writes except for the WRITE\_PROTECT command (bit5 and bit6 must be 0) Copies all current register settings in the module into non-volatile memory (EEPROM) on the STORE\_DEFAULT\_ALL 11 module. Takes about 50ms for the command to execute.\* Restores all current register settings in the module from values in the module non-volatile 12 RESTORE\_DEFAULT\_ALL memory (EEPROM) Copies the current register setting in the module whose command code matches the value in the data byte into non-volatile memory (EEPROM) on the module 4 13 STORE\_DEFAULT\_CODE **Bit Position** 6 0 7 5 3 2 1 Access w w w w w w w w Function Command code Restores the current register setting in the module whose command code matches the value in the data byte from the value in the module non-volatile memory (EEPROM) 14 RESTORE\_DEFAULT\_CODE **Bit Position** 7 6 5 4 з 2 0 1 Access w w w w w w w w Function Command code The module has MODE set to Linear and Exponent set to -13. These values cannot be changed **Bit Position** 4 7 6 5 3 2 1 0 20 VOUT\_MODE Access r r r r r r r r Function Mode Exponent **Default Value** 0 0 0 1 0 0

\*NOTE: The EEPROM memory can be completely written in entirety (for example, using STORE\_DEFAULT\_ALL command) only four times. During the situation of partial rewrites, numerous writes are available within the confines of the available memory (for example, using STORE\_DEFAULT\_CODE command).

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Hex	Command				Brie	ef Desci	ription					Non-Volatile
Code		Apply a fixed offset	voltage	to the e			-	d value	Expond	nt is five	ad at -12	Memory Storage
		Format	voitage					nt binar			u at -15.	
		Bit Position	7	6	5	4	3	2	y 1	0		
		Access	r/w	r/w	r/w	r/w	r/w	∠ r/w	r/w	r/w		
		Function	17 VV	17 VV	1/ 1/		Byte	1/ W	17 VV	17 VV		
22	VOUT_TRIM	Default Value	0	0	0	0	буtе 0	0	0	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	∠ r/w	r/w	r/w		
		Function	17 W	17 W	1/ W		Byte	1/ W	1/ W	1/W		
		Default Value	0	0	0	0	Буце 0	0	0	0		
		Sets the target volta	-	-	-	-	-	-	-	-		
			ige for fi							-15.	1	
		Format Bit Position	7	6	5	4	1	nt binar 2	y 1	0		
		Access	r	r/w	r/w	r/w	3 r/w	∠ r/w	r/w	r/w	-	
			r	r/w	r/w		,	r/w	r/w	r/w	-	
25	VOUT_MARGIN_HIGH	Function	0	0	0		Byte	1	0	1	-	YES
		Default Value	0	0	0	1 4	0	1	0	1	-	
		Bit Position								-	-	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	-	
		Function	0	0	0	1	Byte					
		Default Value	0	0	0	1	1	1	1	1		
		Sets the target volta	ige for n		-					-13	1	
		Format		1	· · · ·	1	· ·	nt binar	í –			
		Bit Position	7	6	5	4	3	2	1	0	-	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	-	
26	26 VOUT_MARGIN_LOW	Function					Byte					YES
		Default Value	0	0	0	1	0	0	0	1		_
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function		1	1	1	Byte		1			
		Default Value	0	1	0	0	1	0	0	0		
		Sets the scaling of the Sets the scaling of the Sets The Sets The Sets The Sets The Sets The Sets Sets Sets Sets Sets Sets Sets Set	e interna	al refere								
		by the value of this	parame								1	
		Format	_					nt binar		-	4	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r	r/w	r/w	4	
2A	VOUT_SCALE_MONITOR	Function		1	xponen	1			Mantiss		4	YES
	VOOT_JOALL_WOWTOK	Default Value	1	0	1	1	1	0	1	0		123
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function		1	1	1	ntissa		1			
		Default Value	0	0	0	0	0	0	0	0	1	
		*For VOUT_SCALE_M										
		1.         between 0.1           2.         Between 0.5           3.         >1.0 use ex	ponent of -9	)								
		Sets the value of inp	out volta	ige at w	hich the	module	e turns o	on. Expo	nent is	fixed at	-6	
		Format		L	inear, t	wo's coi	mpleme	nt binar	'y			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
25		Function		E	Exponer	nt			Mantiss	а		VEC
35	VIN_ON	Default Value	1	1	0	0	1	0	1	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Mar	ntissa					
		Default Value	0	0	1	1	0	0	1	1		
<u> </u>						. –			. –		1	I

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Hex	Command		Brief Description											
Code		Sets the value of inp		ore at w				ff Evpo	nent is t	fixed at	-6	Memory Storage		
		Format				wo's con				ixeu at	-0			
		Bit Position	7	6	5	4	3	2	y 1	0				
		Access	r	r	r	r	r	r	r	r				
		Function	•		Exponen				Mantissa					
36	VIN_OFF	Default Value	1	1	0	0	1	0	1	0		YES		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function	-	.,	.,	Man		.,	.,	.,				
		Default Value	0	0	0	1	0	0	1	1				
		Returns the value of	f the gai	n correc	tion ter	m used	to corre	ct the n	neasure	d outpu	t current			
		Format				vo's con								
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r/w				
		Function			xponen				Mantissa		1			
38	IOUT_CAL_GAIN	Default Value				based or	n factor				1	YES		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				Man	tissa							
		Default Value		V: V	ariable	based or	h factory	/ calibra	tion					
		Returns the value of	f the off							ed outp	ut current			
		······································												
		Formet	1		:						1			
		Format Bit Position	7	6	Inear, t	vo's con 4	npiemer 3	nt binar 2	y 1	0				
							-			-				
39	IOUT_CAL_OFFSET	Access	r	r	r	r +	r	r/w	r	r		YES		
00		Default Value	Function         Exponent         Mantissa           fault Value         V: Variable based on factory calibration											
		Bit Position	7	6	5	4	3	2	1	0				
		Access	, r	r	r/w	r/w	r/w	r/w	r/w	r/w				
		Function			1/ 1	Man		1/ 🗤	1/ 1	1/ 1				
		Default Value		V·V	ariahle	pased or		<i>c</i> alibra	tion					
		Sets the voltage leve	el for an							-13				
		Format				wo's co				10.	1			
		Bit Position	7	6	5	4	3	2	y 1	0	-			
				-	-	-	-		-		-			
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	4			
40	VOUT OV FAULT LIMIT	Function		1	1	-	Byte	1	1	1	4	YES		
		Default Value	0	0	0	1	0	1	1	0	_	113		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				Low	Byte				1			
		Default Value	0	1	1	0	0	1	1	0	1			
		Instructs the module	e on the	action					t overv	oltage fa	ault			
		Format		-	1	Unsigne			-		4			
		Bit Position	7	6	5	4	3	2	1	0	4			
41	VOUT_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r	4	YES		
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	х	х	х				
			[1]	[0]			L - 3		1					
		Default Value	1	0	1	1	1	0	0	0				

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Hex	Command		Brief Description											
Code		Sets the value of our	tout vol	tage at a	which +h	ne modu	le geno	rates w	arning f		voltage	Memory Storage		
		Exponent is fixed at	-	lage at		ie mout	ne gene	ates we	arining li		onage.			
		Format	15	1	inear t	wo's cor	npleme	nt hinar	v					
		Bit Position	7	6	5	4	3	2	, 1	0				
		Access	r	r	r	r	r	r	r	r				
42	VOUT_OV_WARN_LIMIT	Function			xponen				Mantiss			YES		
12		Default Value	0	0	0	1	0	1	0	1		125		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function		, í			tissa	,		, ,				
		Default Value	0	0	1	0	0	0	0	1				
		Sets the value of our	tnut vol	tage at y	which th	ne modu	ile gene	rates wa	arning f	or under	-voltage			
		Exponent is fixed at	-	tuge ut	willen ei	ic mout	ne gene		anning is	or under	voitage.			
		Format		l	inear. t	wo's cor	npleme	nt binar	v					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r/w				
43	VOUT_UV_WARN_LIMIT	Function			xponen				Mantiss			YES		
		Default Value	0	0	0	1	0	0	0	1				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				Man	tissa							
		Default Value	0	1	0	0	1	0	0	0				
		Sets the voltage leve	el for an	output	undervo	oltage fa	ault. Exc	oonent i	s fixed a	at -13.				
		-	Format Linear, two's complement binary											
		Bit Position	7	6	5	4	3	2	y 1	0				
		Access	r	r	r	r	r	r/w	r	r				
		Function			xponen				Mantiss					
44	VOUT_UV_FAULT_LIMIT	Default Value	0	0	0	1	0	0	0	0		YES		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					tissa	,		, ,				
		Default Value	0	1	0	1	0	0	0	0				
		Instructs the module	on the	action	to take i	in resno	nse to a	n outou	t under	voltage	fault			
		Format		action			d Binary	-	t unuer	voitage	lault			
		Bit Position	7	6	5	4	3	2	1	0				
45	VOUT_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES		
			RSP	RSP										
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	Х	Х	Х				
		Default Value	1	0	1	1	1	0	0	0				
		Sets the current leve	el for an	output	overcur	rent fau	ılt (cann	ot be cł	nanged)					
		Format		L	inear, t	wo's cor	npleme	nt binar	v					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r/w	r	r				
46		Function		I	xponen	nt			Mantiss	а		YES		
40	IOUT_OC_FAULT_LIMIT	Default Value	1	1	1	0	0	0	1	1		TE3		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				Man	tissa							
		Default Value	0	0	0	0	1	1	1	1				

# GE

# 80A GigaDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

		Sets the value of cu	rrent lev	vel at wh	nich the	module	genera	tes warı	ning for	overcur	rent.	
		Format		L	inear, t	vo's cor	npleme	nt binar	у			
	4A IOUT OC WARN LIMIT	Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r/w		
4.0		Function		E	xponen	t		I	Mantiss	а		YES
4A	IOUT_OC_WARN_LIMIT	Default Value	1	1	1	0	0	0	1	0		TES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	itissa					
		Default Value	1	1	1	1	1	1	1	1		

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Hex	Command		Brief Description											
Code								<u> </u>				Memory Storage		
		Sets the temperatur	e level :											
		Format					npleme	1	<u> </u>	1				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r/w	r	r				
4F	OT_FAULT_LIMIT	Function		E	xponen	t			Mantiss			YES		
-11		Default Value	1	1	1	0	1	0	1	1		TES		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					tissa		-					
		Default Value	1	1	1	0	0	1	1	1				
		Configures the over	temper	ature fa	ult resp	onse								
		Format					d Binary	/						
		Bit Position	7	6	5	4	3	2	1	0	1			
50	OT_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES		
		Function	RSP	RSP		-	-	v	v	v				
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	Х	Х	Х				
		Default Value	1	0	1	1	1	0	0	0				
		Sets the over tempe	erature v	warning	level in	°C								
		Format		L	.inear, t	wo's cor	npleme	nt binar	У					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
51	OT_WARN_LIMIT	Function	Exponent Mantissa							YES				
01	0.7	Default Value	1	1	1	0	1	0	1	1		113		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				Man	tissa							
		Default Value	1	0	0	1	0	1	1	0				
		Configures the VIN o	overvolt	age faul	t respor	nse.					•			
		Format		<u> </u>			d Binary	/						
		Bit Position	7	6	5	4	3	2	1	0				
056	VIN_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES		
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	х	х	х				
		Default Value	[1] 1	[0] 0	0	0	0	0	0	0				
		Sets the value of the	e input v	voltage t	hat cau	ses inpu	t voltag	e low w	arning	Exponer	nt fixed at -6			
		Format					npleme							
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
		Function			xponer				Mantiss		1			
57	VIN_OV_WARN_LIMIT	Default Value	1	1	0	1	0	0	1	1	1	YES		
	-	Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function		.,	.,		itissa	.,	.,	.,				
		Default Value	1	0	0	1	0	0	1	1				
			-	5	3	· -		3	· -	· -	1			

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Hex Code	Command		Non-Volatile Memory									
coue		Sets the value of the	e input v	oltage t	hat cau	ses inpu	t voltag	e low w	arning	Exponen	t fixed	Storage
		at -6		onuge (		000 mp0	e ronu <sub>b</sub>			Enpoiren	e intea	
		Format		1	inear. t	wo's coi	npleme	nt binar	v			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
58	VIN_UV_WARN_LIMIT	Function		E	Exponer	nt			Mantiss	а		YES
		Default Value	1	1	0	0	1	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	itissa					
		Default Value	0	1	0	0	0	0	0	0		
		Sets the value of the	e input v	oltage t	hat cau	ses an ir	nput und	dervolta	ge fault	. Expone	ent	
		fixed at -6.										
		Format		L	.inear, t	wo's coi	npleme	nt binar	у			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
59	VIN_UV_FAULT_LIMIT	Function		E	Exponer	nt			Mantiss	a		YES
		Default Value	1	1	0	0	1	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	itissa			-		
		Default Value	0	0	0	0	1	1	0	1		
		Instructs the modul	e on wh	at actio	n to tak	e In resc	onse to	an inpu	it under	voltage	fault.	
		Format										
		Bit Position	7	6	5	Unsigne 4	3	2	1	0		
5A	VIN_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	х	х	х		
		Default Value	1	0	1	1	1	0	0	0		
				l at whi	ah +h a [		ain is as	orted b	ich Fur	on ont is	fived	
		Sets the output volt at -13.	age ieve							bonentis	s iixeu	
		Format	_			wo's coi						
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		1/50
5E	POWER_GOOD_ON	Function	0	0	0		Byte	0	1	0		YES
		Default Value	7	6	0	1 4	0	2	1	0		
		Bit Position Access	r/w	r/w	r/w	r/w	r/w	z r/w	r/w	r/w		
		Function	1/ W	1/ W	1/ W		Byte	1/ W	1/ 1/	17 99		
		Default Value	0	0	1	1	byte 1	1	1	1		
		Sets the output volt fixed at -13.	-				_	_		_	ıt is	
		Format			Linear.	two's co	mplem	ent bina	ry			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
5F	POWER GOOD OFF	Function		,	,		h Byte	,	,	,		YES
		Default Value	0	0	0	1	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function		, <u>·</u>			v Byte					
		Default Value	0	1	0	0	1	0	0	0		
L	1		-		-		-	-	-	v		

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

11						,		,					Non-Volatile Memory	
Hex Code	Command		Brief Description											
		Sets the delay time	in ms of	the out	put volt	age du	uring sta	rtup.					Storage	
		Format			Linear,	two's	compler	nent bina	ary					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r/w				
		Function			Exponen	t			Mantis	sa				
60	TON_DELAY	Default Value	1	1	1	1	1	0	0	0			YES	
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function	-			N	lantissa							
		Default Value	0	0	0	0	0	0	0	0				
		Sets the rise time in	ms of t	he outp	ut volta	ge dur	ing start	up						
		Format			Linear,	two's	compler	nent bina	ary					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	R	r	r	r	r	r/w				
64	TON DICE	Function		E	Exponen	t			Mantis	sa			266	
61	TON_RISE	Default Value	1	0	1	1	1	0	1	1			YES	
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				N	lantissa							
		Default Value	1	1	1	1	1	1	1	1				
		Sets the delay time	in ms o	f the ou	utput vo	ltage c	during tu	ırn-off						
		Format			Linear,	two's	compler	nent bina	ary					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	R	r	r	r	r	r/w				
64		Function		E	Exponen	t			Mantis	sa			VEC	
64	TOFF_DELAY	Default Value	1	1	1	1	1	0	0	0			YES	
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				N	lantissa							
		Default Value	0	0	0	0	0	0	0	0				
		Sets the fall time in	ms of tl	he outp	ut volta	ge dur	ing turn	-off						
		Format			Linear,	two's	compler	nent bina	ary					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	R	r	r	r	r	r/w				
C.F.		Function		E	Exponen	t			Mantis	sa			VEC	
65	TOFF_FALL	Default Value	1	0	1	1	1	0	1	1			YES	
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				N	lantissa							
		Default Value	1	1	1	1	1	1	1	1				
		Returns one byte of	informa	ation wi	th a sun	nmary	of the n	nost critic	al modu	ule fault	S			
		Format				Un	signed E	Binary						
70		Bit Position	7	6	5		4	3	2	1	0			
78	STATUS_BYTE	Access	r	r	R		r	r	r	r	r		NO	
		Flag	Х	OFF	VOUT_	0V 10	UT_OC	VIN_UV	TEMP	CML	OTHER			
		Default Value	0	0	0		0	0	0	0	0			
		Returns two bytes o	-		-	mmarv	-	-	-			5		
		Format					nsigned							
		Bit Position	7	6	!	5	4	3	2	1	0	1		
		Access	r	r		R	r	r	r	r	r			
		Flag		IOUT_C		x	X	PGOO		X	X			
79	STATUS_WORD	Default Value	0	0 0			0	0		0	0		NO	
		Bit Position	7	6		5	4	3	2	1				
		Access	r	r		R	r	r	r	r	r			
		Flag	X	OFF				C VIN U				2		
		Default Value	0	0		) )	0		0	0	0	Ì		
		Belault Value	0	U			0	0	0	0	U		1	

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Hex	Command	Brief Description												Non-Volatile		
Code		Returns one byte of	informa	tion			-		mod	ule's s	uter	it vo	lta	TO TO	atod	Memory Storage
		faults	morma	tion v	vitri tri	e stat	us oi	the	mou	ule s o	սւրւ		nraş	gere	ateu	
		Format				U	Insigr	ned B	inary	/						NO
7A	STATUS_VOUT	Bit Position	7		6	5		4		3	2	1		0	_	NO
		Access	r		r	r		r		r	r	r	_	r	_	
		Flag	VOUT	_ov	X	X	VO	UT_U	JV	X	X	X	_	X	_	
		Default Value	0		0	0		0		0	0	0		0		
		Returns one byte of faults	Informa	tion v	vith th	e stat	us of	thei	moa	ule's o	υτρι	it cu	irre	nt re	ated	
		Format Unsigned Binary														
7B	STATUS_IOUT	Bit Position	7		6 !	5 4			3			2	1	0	_	NO
		Access	r			r r			r			r	r	r		-
		Flag	IOUT_	OC	X	< X	10	OUT_	0C_	WARN	I	Х	Х	Х		
		Default Value	0		0 (	0 0			0			0	0	0		
		Returns one byte of information with the status of the module's input related faults														
		Format					Unsig	ned E	Binar							
7C	STATUS_INPUT	Bit Position		7		6	_	5		4		3	2	1	0	NO
	STATUS_INPUT	Access		r		r		r		r		r	r	r	r	NO
		Flag	VIN_OV	/_FAU		IN_O WARN NG	JI V	'IN_U 'ARNI		VIN_ _FAU		x	Х	х	х	
		Default Value	(	0		0		0		0		0	0	0	0	
		Returns one byte of information with the status of the module's temperature related faults														
		Format	_		<u> </u>			ed Bir				T -	T			
7D	STATUS_TEMPERATURE	Bit Position	7			6		5	4	3	2	1		0		
		Access Flag	r OT_FAULT		OT	r WAR	N	r X	r X	r X	r X	r X	_	r X		
		Default Value	01_17			0		0	0	0	0	0		0		
		Returns one byte of information with the status of the module's communication related faults														
		Format				Ur	nsigne	ed Bir	nary							
		Bit Position	7		6		5	4	3	2		1		0		
7E	STATUS_CML	Access	r		r		r	r	r	r		r		r		
		Flag	Invali Comma		Invali Data		EC ail	х	х	x	Со	her mm ault		x		
		Default Value	0		0	(	0	0	0	0		0		0		
		Returns the value o	f the inpu	ut voli	tage a	pplied	d to th	he m	odul	e. Exp	oner	t is	fixe	d at	-6	
		Format	1							t bina		-	-	-		
		Bit Position	7	6	5		4	3		2		1		0		
		Access	r	r	r		r	r	·	r		r		r		
88	READ_VIN	Function			Expo						Man					
		Default Value	1	1	0		1	0		V 2		/	-	V		
		Bit Position	7 r	6 r	5		4 r	3		2 r	1	1 r		0 r		
		Access Function	r	r	r		r Mar	r ntissa		r	L	r	I	r		
		Default Value	V	V	V		V	V		V	1	/		V		
		Returns the value of	-				-	-				-				
		Format			-					t bina				-		
		Bit Position	7	6	5		4	3		2	ŕ –	1		0		
		Access	r	r	r		r	r	·	r		r		r		
8B	READ_VOUT	Function	ļ					ntissa			-		-			
		Default Value	V	V	V		V	V		V	-	/	_	V		
		Bit Position	7	6	5		4	3		2	-	1		0		
		Access Function	r	r	r		r Mar	r ntissa		r		r	<u> </u>	R		
		Default Value	V	V	V		V	ntissa V	_	V	\ \	/		v		
			v	v	V		v	V		v	1	v		v		

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Hex				•	inuea)							Non-Volatile				
Code	Command		Brief Description													
			Returns the value of the output current of the module       Format     Linear, two's complement binary													
			_							<u> </u>						
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
8C	READ_IOUT	Function	1	1	Exponen	1			Mantissa							
		Default Value	1 7	1 6	1	0	0	V 2	V 1	V						
		Bit Position Access	r	r	5 r	4 r	r s	2 r	1 r	0 R						
		Function	-		1		ntissa		I	ĸ						
		Default Value	V	V	V	V	V	V	V	V						
								-	-							
		Format		I	inear, t	wo's coi	mpleme	nt binar	Ϋ́							
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
		Function			Exponen	it			Mantissa	a						
8D	READ_TEMPERATURE_1	Default Value	1	1	1	0	1	V	V	V						
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
		Function			1	1	ntissa		1							
		Default Value	V	V	V	V	V	V	V	V						
		Returns the module														
		Returns the module	PWM c													
		Format		1		1	mpleme		í.							
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
8E	READ_TEMPERATURE_2	Function	4	1	Exponen	1	4		Mantissa							
	_	Default Value	1	1	1	0	1	V 2	V 1	V						
		Bit Position	7 r	6 r	5 r		3 r	2 r	1 r	0 r						
		Access Function	r	r	r	r Man	r ntissa	r	r	r						
		Default Value	v	V	V	V	V	V	V	V						
		Returns the switchir					-		-		id is					
		read only, consisting									-					
		Format			inear, t	wo's coi	mpleme	nt binar	ý							
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
95	READ_FREQUENCY	Function			Exponen	it		I	Mantissa	9						
		Default Value	0	0	0	0	0	0	0	1						
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
		Function				1	ntissa	^	_	_						
		Default Value	1	0	0	1	0	0	0	0						
		Returns one byte in	dicating	the mo					ec. 1.1 (r	ead only	/)					
		Format		-			ed Binary									
98	PMBUS_REVISION	Bit Position	7	6	5	4	3	2	1	0		YES				
		Access	r O	r	r 1	r O	r O	r O	r 1	r O						
		Default Value	U	0		U	U	U	1	U						
		Returns the minimu	m input							read on	ly)					
		Format		1			mpleme									
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
AO	MFR_VIN_MIN	Function			Exponen				Mantissa			YES				
		Default Value	1	1	0	0	0	0	1	0						
		Bit Position	7 r	6	5	4 r	3	2	1	0						
		Access	r	r	r	r Mar	r	r	r	r						
		Function Default Value	0	1	1	0	ntissa 0	1	1	0						
			U	1 1	1 1	0	U	1 1	1	U						

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

		т	able 6	(conti	nued)								
Hex Code	Command			6	Brief De	scrip	otion						Non-Volatile Memory Storage
		Returns the minimu	ım outpı	ut voltag	e possib	ole fr	om the	e modu	ile (read	d only)			
		Format			inear, tv								
		Bit Position	7	6	5	4		3	2	1	0		
		Access	r	r	r	r		r	r	r	r		
		Function				N	1antissa	a					
A4	MFR_VOUT_MIN	Default Value	1	0	1	0	(	)	0	1	1		YES
		Bit Position	7	6	5	4	3	3	2	1	0		
		Access	r	r	r	r		r	r	r	r		
		Function				N	1antissa	a					
		Default Value	1	1	0	1	(	C	1	1	0		
		Returns module nar	ne infor	mation (	read on	ıly)							
		Format					gned Bi	nary					
		Bit Position	7	6	5	4		3	2	1	0		
		Access	r	r	r	r	1	r	r	r	r		
		Function				R	eserve	d					
D0	MFR_SPECIFIC_00	Default Value	0	0	0	0		C	0	0	0		YES
		Bit Position	7	6	5	4	3	3	2	1	0		
		Access	r	r	r	r		r	r	r	r		
		Function			Module	e Nar	ne	I		Reser	ved		
		Default Value	0	0	1	0	-	1	0	0	0		
-		Returns module info	ormation	n (read o	only)								
		Format		i (i cuu u	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Ung	signed	Binary					
		Bit Position	7	6	5	-	4	3	2	1	C	)	
		Access	r	r	r		r	r	r	r	r		
		Function		· ·	- I - '		odule N		1 ·				
		Default Value	0	1	0		1	0	0	1	C	)	
		Bit Position	7	6	5		4	3	2	1	C		
		Access	r	r	r		r	r	r	r	r		
		Function				M	odule N						
		Default Value	0	0	1		1	1	1	0	C	)	
		Bit Position	7	6	5		4	3	2	1	C	)	
		Access	r	r	r		r	r	r	r	r		
		Function			-	M	odule N	Vame	1		-		
		Default Value	0	0	0		0	0	1	1	C	)	
		Bit Position	7	6	5		4	3	2	1	0		
		Access	r	r	r		r	r	r	r	r		
		Function		1			odule N			-			
D1	MFR SPECIFIC 01	Bit Position	7	6	5		4	3	2	1	C	)	YES
		Access	r	r	r		r	r	r	r	r		. 23
		Function		•		M	odule N	Vame					
		Default Value	0	0	1	1	0	0	0	1	C	)	
		Bit Position	7	6	5		4	3	2	1	C	)	
		Access	r	r	r		r	r	r	r	r		
		Function				M	odule N	Vame					
		Default Value	0	0	1		1	0	0	1	C	)	
		Bit Position	7	6	5		4	3	2	1	C	)	
		Access	r	r	r		r	r	r	r	r		
		Function		_		M	odule N	lame					
		Default Value	0	0	0		1	0	0	0	C		
		Bit Position	7	6	5		4	3	2	1	C	)	
		Access	r	r	r		r	r	r	r	r		
		Function		1	-		odule N		1	-			
		Default Value	0	0	0		0	0	1	1	0		
		Bit Position	7	6	5		4	3	2	1	C		
		Access	r	r	r		r	r	r	r	r		
													1

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Harry		Tab	le 6 (c	ontint	ieu)	_	_	_				Non-Volatile	
Hex Code	Command		Brief Description										
DB	MFR_VOUT_MARGIN_HIGH	Returns the target v	/oltage	for mar	gining th	ne outpu	ut high.	Expone	nt is fixe	ed at -13	J.	Memory Storage YES	
		Format			Linear, t	wo's co	mplem	ent bina	ry				
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r	r	r			
		Function			Exponer	nt			Mantiss	a			
		Default Value	V	V	V	V	V	V	V	V			
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r	r	R	_		
		Function		V		V	ntissa V	V	V	V	-		
		Default Value	V	V	V	V	V	V	V	v			
		Returns the target ve	oltage f		_			•		at -13			
		Format	_		inear, tv		· ·			-			
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r	r	r			
DC	MFR_VOUT_MARGIN_LOW	Function	M	V	V	Man		V	V	V		YES	
		Default Value Bit Position	V 7	V 6	V 5	V 4	V 3	2	V 1	V 0			
		Access	r	r	r	r r	r	r z	r	r			
		Function			I ' I	' Man			•				
		Default Value	V	V	V	V	V	V	V	V			
		Returns the index de					d to the				ule		
		Format	inveu II	on the		Jnsigne			μιι υι ι		uiC.		
		Bit Position	7	6	5	4	3	2	1	0			
DD	MFR_RTUNE_INDEX	Access	r	r	r	r	r	r	r	r		YES	
		Function	-	-		Rese			-				
		Default Value	V	V	V	V	V	V	V	V			
		Gets or sets the writ	e prote	ction st	atus of v	arious P	MBus c	omman	ds. Whe	n a bit i	s set. the		
		corresponding PMB									,		
		Format			l	Jnsigne	d Binary	/					
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r	r	r			
		Function				Rese							
		Default Value	0	0	0	0	0	0	0	1			
		Bit Position	15	14	13	12	11	10	9	8			
		Access	r	r	r	r	r	r	r	r			
DF	MFR_WRITE_PROTECT	Function	1	See 1	e Descrip			1	1	1		YES	
		Default Value Bit 0: ON OFF CONF	1	T	1	1	1	1	1	1			
		Bit 1: IOUT_CAL com		omnris	ing both		AL GAI	N and IC	DUT CA	L OFFSF	Т		
		Bit 2: IOUT_OC_FAU			0.5000		0.1						
		Bit 3: IOUT_OC_FAU											
		Bit 4: OT_FAULT_LIN											
		Bit 5: OT_FAULT_RES											
		Bit 6: TOFF_MAX_W			-								
		Bit 7: MFR_EXT_TEN		_	I								
		Bit 8: MFR_PHASE_C Bit 9: MFR_SPECIFIC		'L									
		Gets or sets the targ		ut volta	ge when	switchi	ing off t	he devic	e. in vo	lts. Setti	ng a non-		
		zero value here will e							-,				
		Format		l	inear, tv	vo's cor	npleme	nt binar	y				
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r/w	r	r			
EO	MFR_VOUT_OFF	Function			xponen				Mantissa			YES	
		Default Value	1	1	0	0	0	0	0	V			
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r/w	r/w	r/w	r/w	r/w			
		Function	11	17	14	Man V	1	17	V	11			
		Default Value	V	V	V	v	V	V	v	V			

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

#### Table 6 (continued)

Hex Code	Command				Brief	Descrip	tion					Non-Volatile Memory Storage
		Allows user to enable	_	YES								
		Format	Unsigned Binary									
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r/w	r/w	r/w	r/w		
		Function				Rese	erved					
		Default Value	0	0	0	0	0	0	0	0		
E7		Bit Position	15	14	13	12	11	10	9	8		
E/	MFR_FEATURES_CONTROL	Access	r	r	r	r	r	r	r	r		
		Function		See	e Descrip	tion Be	low					
		Default Value	0	0	0	0	0	0	0	0		
		Bit 0: VTRACK ENAB	LE, 0 = [	Disabled	l; 1 = En	abled					•	
		Bit 1: SYNC ENABLE,	0 = Disa	abled; 1	= Enabl	ed						
		Bit 2: SYNC IN/OUT,	0 = Syn	c signal	input; 1	= Sync	Signal O	utput				
		Bit 3: SYNC Edge, 0 =	= Rising	Edge								

#### Digital Power Insight (DPI)

GE offers a software tool that set helps users evaluate and simulate the PMBus performance of the GDT080 modules without the need to write software.

The software can be downloaded for free at <u>http://go.ge-energy.com/DigitalPowerInsight.html</u>. A GE USB to I2C adapter and associated cable set are required for proper functioning of the software suite. For first time users, the GE DPI Evaluation Kit can be purchased from leading distributors at a nominal price and can be used across the entire range of GE Digital POL Module.

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Thermal Considerations**

GE

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 38. The preferred airflow direction for the module is shown in Figure 39.



Figure 38. Thermal Test Setup.



#### Figure 39. Preferred airflow direction and location of hotspot of the module (Tref).

The thermal reference points,  $T_{ref}$  used in the specifications are also shown in Figure 39. For reliable operation the temperatures at these points should not exceed 120°C. The output power of the module should not exceed the rated power of the module (Vo,set x Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### Example Application Circuit

<b>Requirements:</b>
----------------------

Vin:	12V
Vout:	1.2V
lout:	80A max., worst case load transient is from 20A to 60A
∆Vout:	1.5% of Vout (18mV) for worst case load transient
Vin, ripple	2% of Vin (220mV p-p)





CI1	Decoupling cap - $1x0.1\mu$ F/16V ceramic capacitor (e.g. Murata LLA215R71A224MA14)
CI2	6x22μF/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)
CI3	470μF/16V bulk electrolytic
CO1	Decoupling cap - 1x0.047µF/16V ceramic capacitor (e.g. Murata LLA215R71A224MA14)
CO2	6 x 47μF/6.3V ceramic capacitor (e.g. Murata GRM31CR60J476ME19)
CO3	5 x 1000μF/2.5V Polymer (e.g. Sanyo Poscap)
RTune	4.22kohms SMT resistor (can be 1206, 0805 or 0603 size)
RTrim	$2 \mathrm{k} \Omega$ SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Mechanical Outline**

Dimensions are in millimeters and (inches). Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated] x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)





SIDE VIEWS

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Recommended Pad Layout**



### **Pinout Details**

PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	GND	15	SEQ	29	SMBALERT#
2	VIN	16	VS+	30	NC
3	GND	17	SIG_GND	31	NC
4	VIN	18	NC	32	NC
5	GND	19	PGOOD	33	NC
6	GND	20	ADDR0		
7	VOUT	21	NC		
8	VOUT	22	SYNC		
9	GND	23	ADDR1		
10	GND	24	RTUNE		
11	VOUT	25	ON/OFF		
12	VOUT	26	CLK		
13	VS-	27	NC		
14	TRIM	28	DATA		

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Packaging Details**

The 80A GigaDLynx<sup>™</sup> 80A modules are supplied in tape & reel as standard. Modules are shipped in quantities of 80 modules per reel. All Dimensions are in millimeters and (in inches).



### **Surface Mount Information**

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

#### **Pick and Place**

The 80A GigaDLynx<sup>™</sup> modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

#### **Nozzle Recommendations**

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 10mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 17 mm.

#### **Bottom Side / First Side Assembly**

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

#### **Lead Free Soldering**

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect longterm reliability.

#### **Pb-free Reflow Profile**

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 40. Soldering outside of the recommended profile requires testing to verify results and performance.

### **Ordering Information**

Please contact your GE Sales Representative for pricing, availability and optional features.

### Table 7. Device Codes

MSL Rating

The 80A GigaDLynx<sup>™</sup> modules have a MSL rating of 3.

#### **Storage and Handling**

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of  $\leq$  30°C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: < 40° C, < 90% relative humidity.



Figure 40. Recommended linear reflow profile using Sn/Ag/Cu solder.

#### Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to *Board Mounted Power Modules: Soldering and Cleaning* Application Note (AN04-001).

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Sequencing	Comcodes
GDT080A0X3-SRZ	4.5 – 14Vdc	0.6 – 2.0 Vdc	80A	Negative	Yes	150037110
GDT080A0X43-SRZ	4.5 – 14Vdc	0.6 – 2.0 Vdc	80A	Positive	Yes	150044134

-Z refers to RoHS compliant parts

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

#### Table 8. Coding Scheme

Package Identifier	Family	Sequencing Option	Output current	Output voltage	On/Off logic	Remote Sense	Options		ROHS Compliance
G	D	Т	080A0	х		3	-SR	-Н	Z
P=Pico U=Micro M=Mega G=Giga	D=Dlynx Digital V = DLynx Analog.	T=with EZ Sequence X=without sequencing	80A	X = programma ble output	4 = positive No entry = negative	3 = Remote Sense	S = Surface Mount R = Tape & Reel	Extra Ground Pins	Z = ROHS6

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